

# **3D Scalar Field Visualization: Volume Rendering**

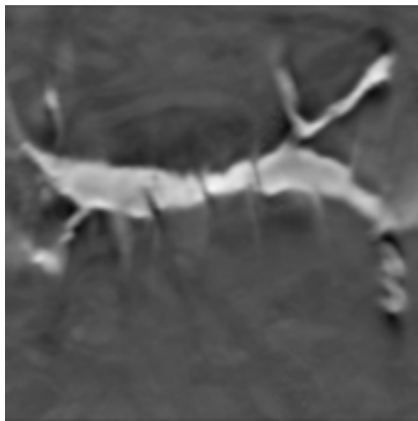
Goal: understand what is DVR and why it is useful; how to compute DVR (important steps); how to perform raycasting

# Iso-surfacing Could Be limited

- Iso-surfacing is "binary"
  - point inside iso-surface?
  - voxel contributes to image?
- Is a hard, distinct boundary necessarily appropriate for all the visualization tasks?

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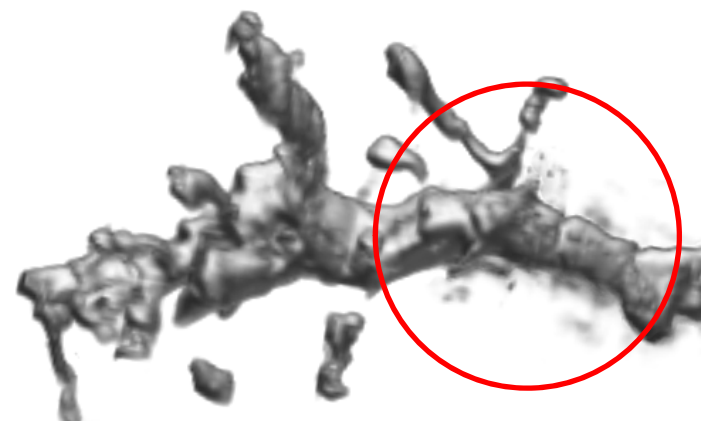
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Slice



Isosurface



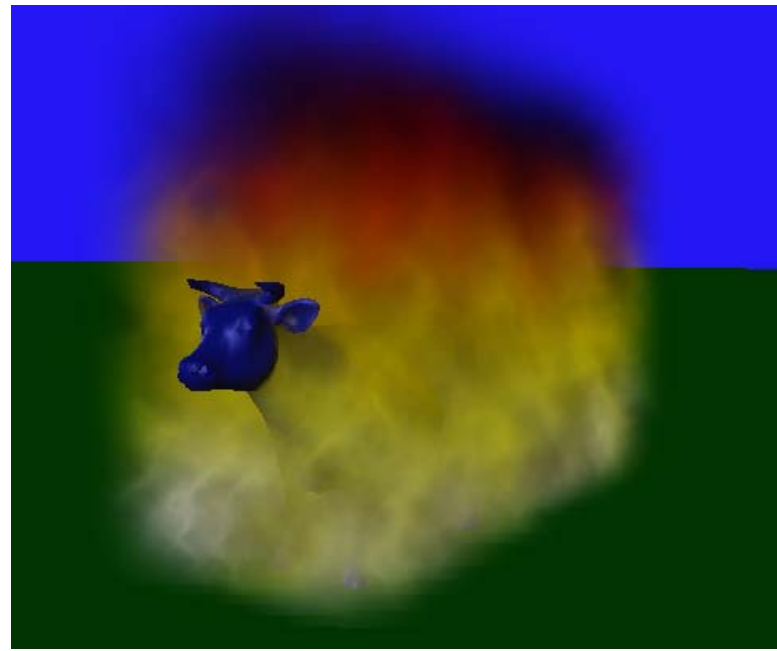
Volume Rendering

# Iso-surfacing Could Be Limited

- Iso-surfacing poor for ...
  - measured, "real-world" (**noisy**) data
  - **Amorphous (fog-like)**, "soft" objects



virtual angiography



bovine combustion simulation

# What is Direct Volume Rendering

- Any rendering process which maps from volume data to an image without introducing **binary distinctions / intermediate** geometry
- How do you make the data visible?

# What is Direct Volume Rendering

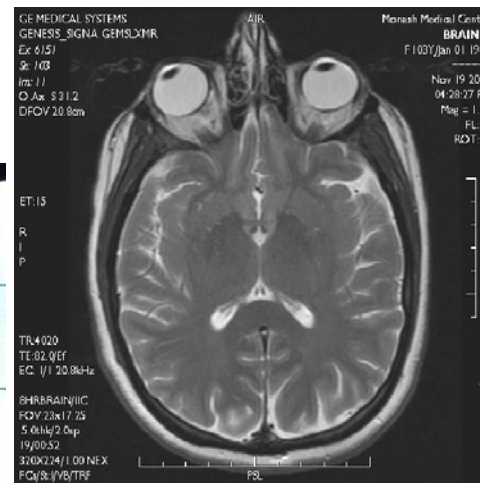
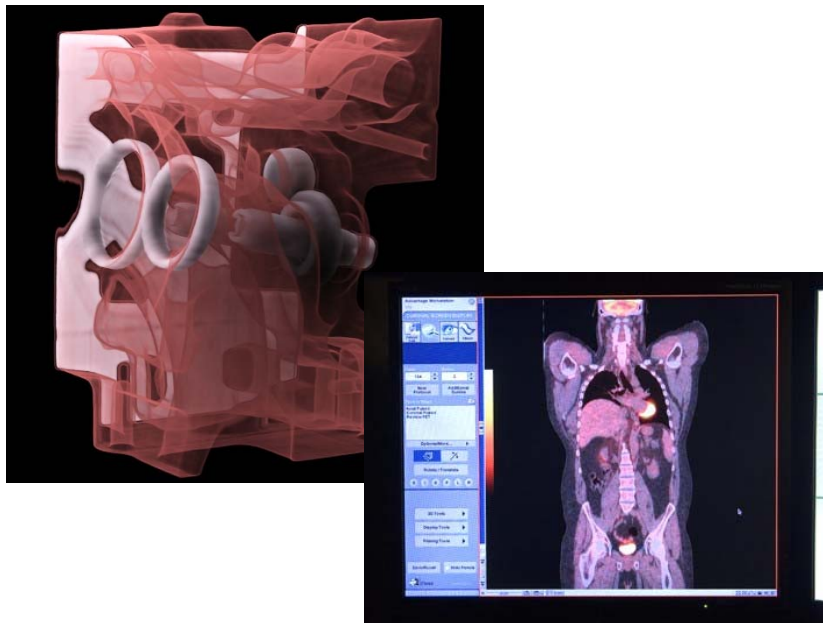
- Any rendering process which maps from volume data to an image without introducing **binary distinctions / intermediate** geometry
- How do you make the data visible? : Via Color and Opacity
- How to achieve that?

# What is Direct Volume Rendering

- Any rendering process which maps from volume data to an image without introducing **binary distinctions / intermediate** geometry
- How do you make the data visible? : Via Color and Opacity
- How to achieve that?
  - The data is considered to represent a **semi-transparent light-emitting medium**
  - Approaches are based on the **laws of physics** (emission, absorption, scattering)
  - The volume data is **used as a whole** (look inside, see interior structures). Think of color plots in 3D!

# Volume Rendering is Useful

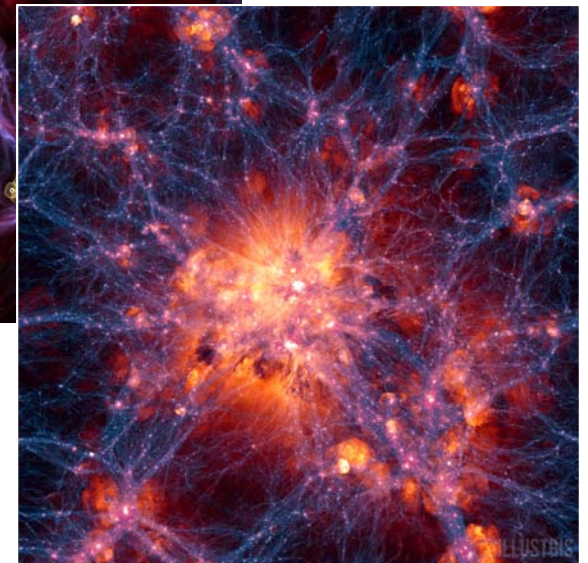
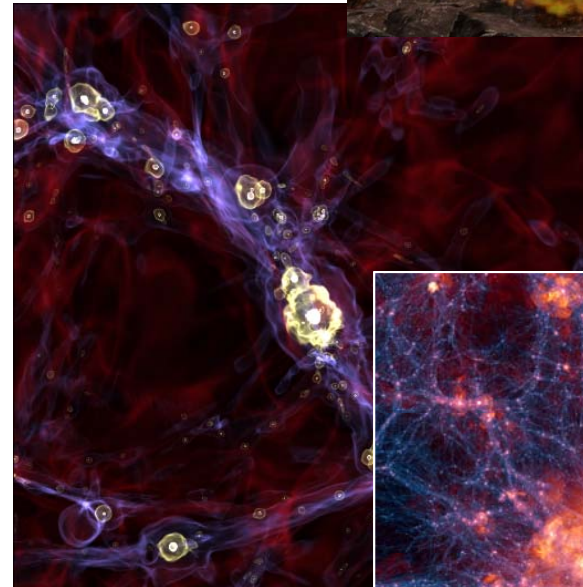
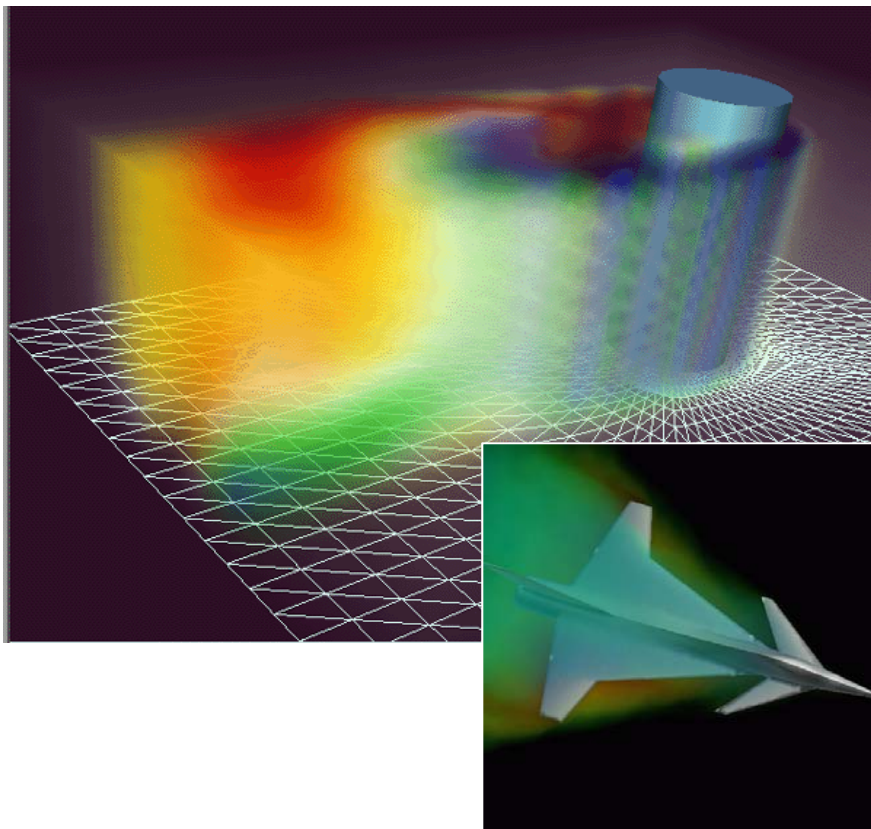
- **Measured sources of volume data**
  - CT (computed tomography)
  - PET (positron emission tomography)
  - MRI (magnetic resonance imaging)
  - Ultrasound
  - Confocal Microscopy





# Volume Rendering is Useful

- **Synthetic** sources of volume data
  - CFD (computational fluid dynamics)
  - Voxelization of discrete geometry

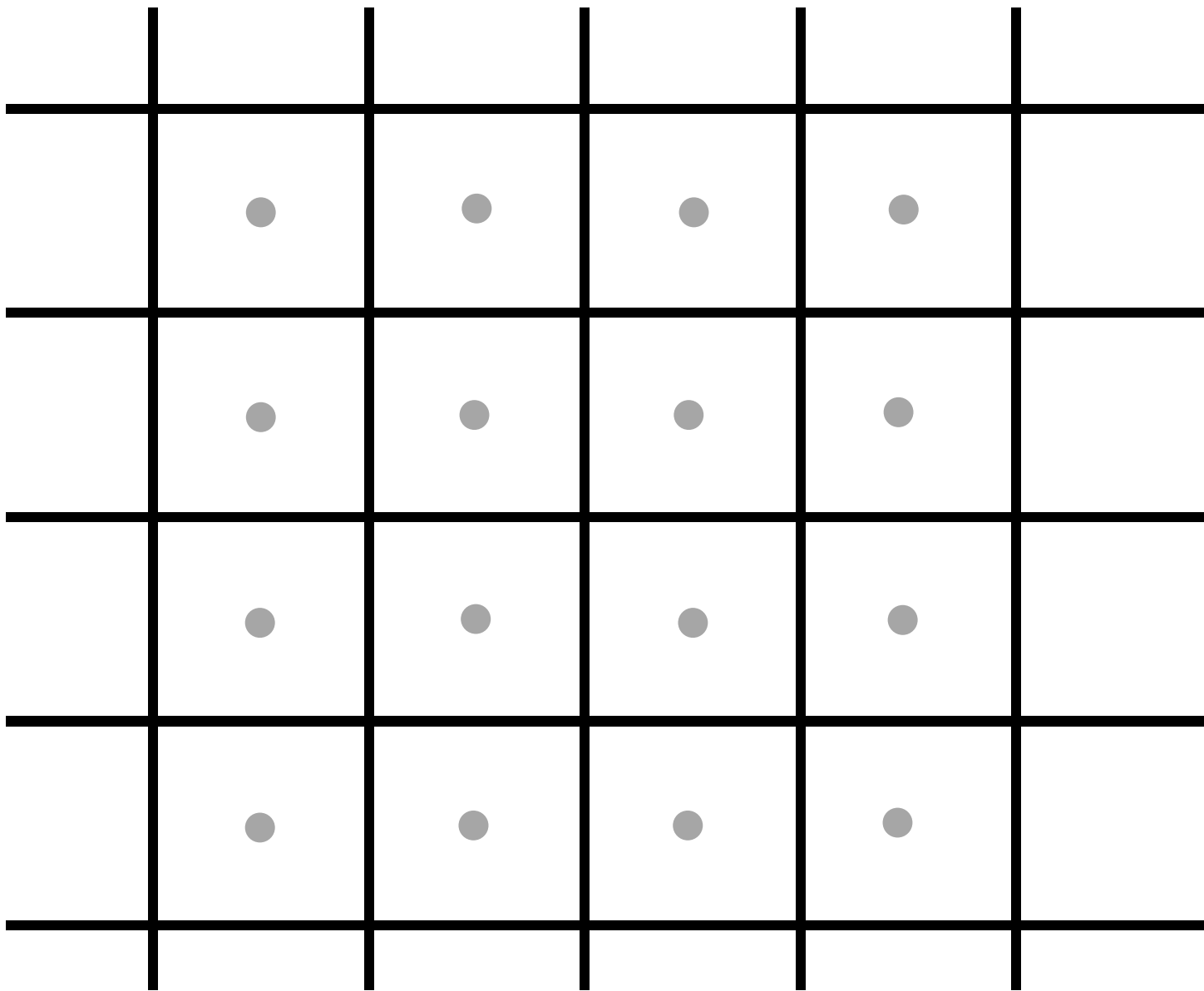


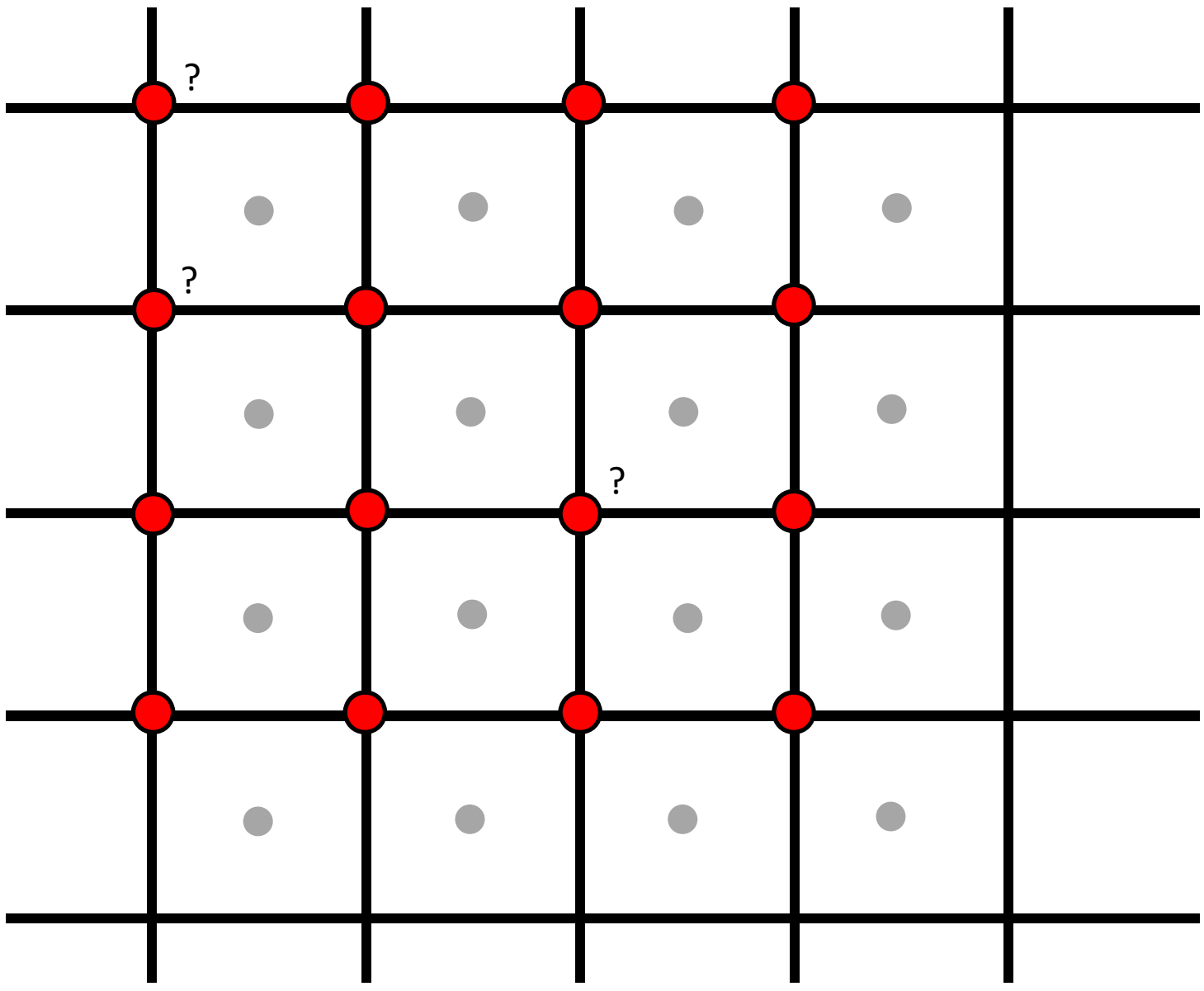
# Data Representation

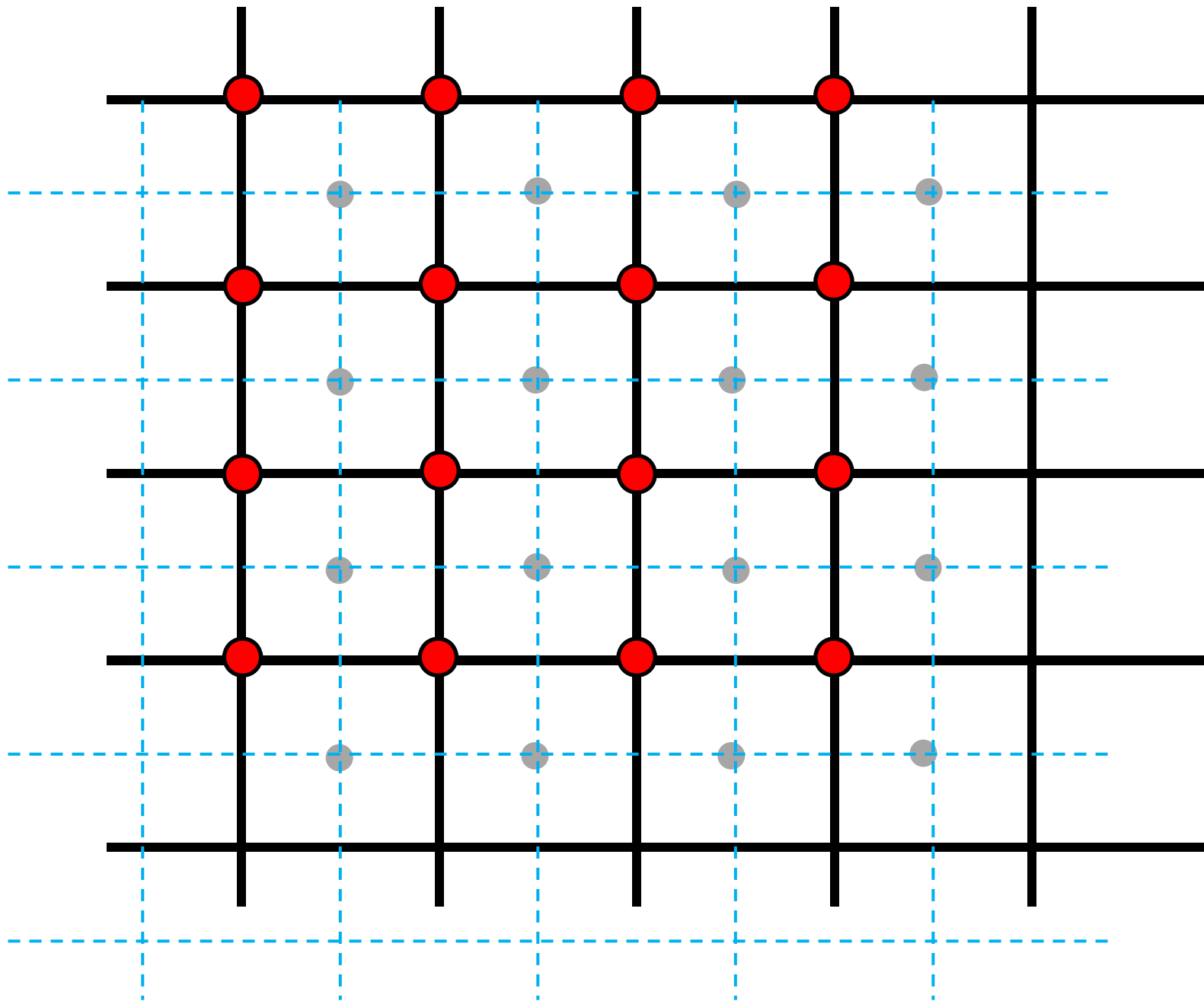
- Volume rendering techniques
  - depend strongly on the **grid type**
  - exist for both structured and unstructured grids
  - are predominantly applied to **uniform grids (3D images)**.
  - for uniform grid, voxels are the basic unit

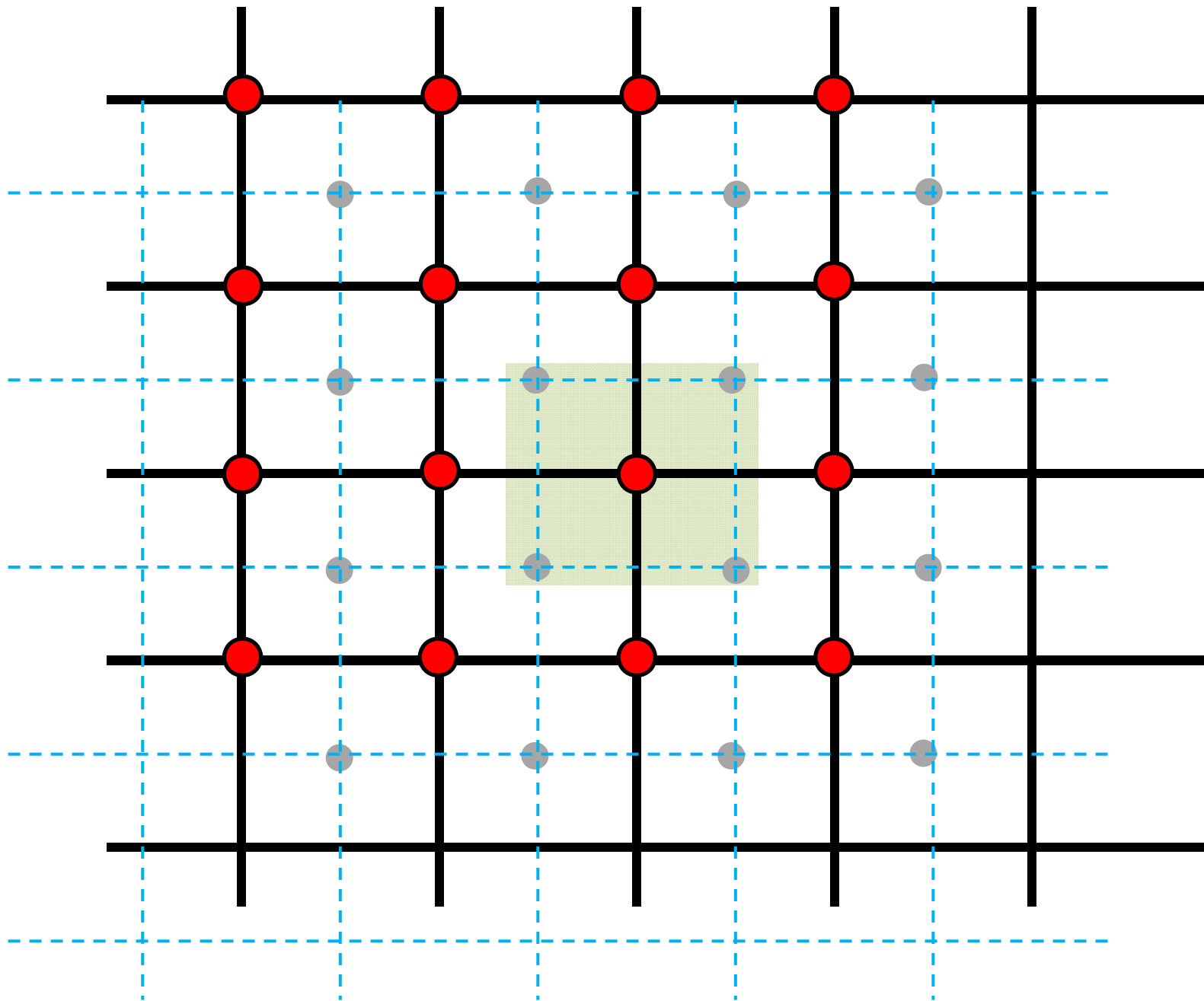
# Data Representation

- Volume rendering techniques
  - depend strongly on the **grid type**
  - exist for both structured and unstructured grids
  - are predominantly applied to **uniform grids (3D images)**.
  - for uniform grid, voxels are the basic unit
- **Cell-centered data for uniform grids**
  - are attributed to cells (pixels, voxels) **rather than nodes**
  - can also occur in (finite volume) CFD datasets
  - **are converted to node data (e.g., for iso-surfacing)**
    - by taking the dual grid (easy for uniform grids,  $n$  cells  $\rightarrow$   $n-1$  cells!)
    - or by interpolating.







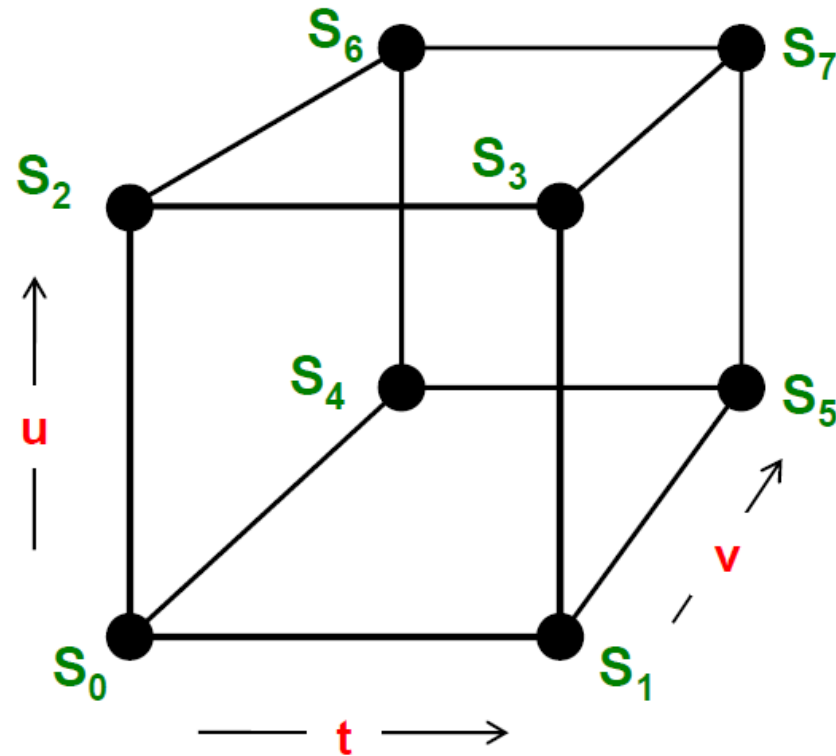


# Important Concepts

- Interpolation
  - **trilinear** common, others possible
- Color and opacity transfer function
  - Turning scalar values to colors
- Gradient
  - direction of fastest change
- Compositing
  - "over operator"



# Trilinear Interpolation



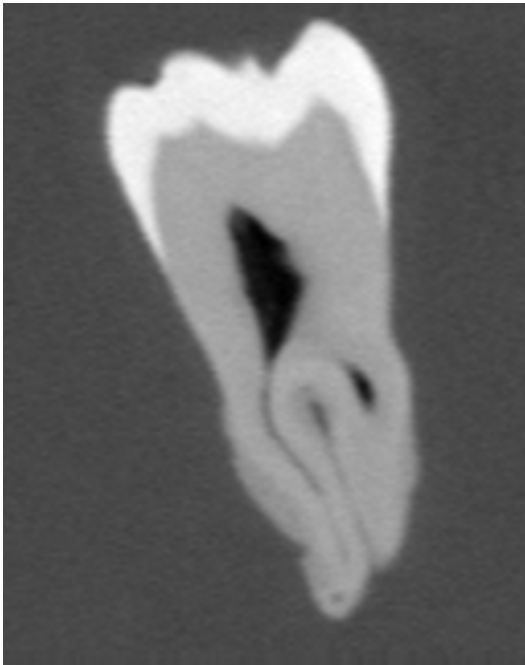
$$S(t, u, v) = (1-t)(1-u)(1-v)S_0 + t(1-u)(1-v)S_1 + (1-t)u(1-v)S_2 + tu(1-v)S_3 + (1-t)(1-u)vS_4 + t(1-u)vS_5 + (1-t)uvS_6 + tuvS_7$$

This is useful, for example, if we have passed an oblique cutting plane through a 3D mesh of points and are trying to interpolate scalar values from the 3D mesh to the 2D plane.

# Color and Opacity Transfer Functions

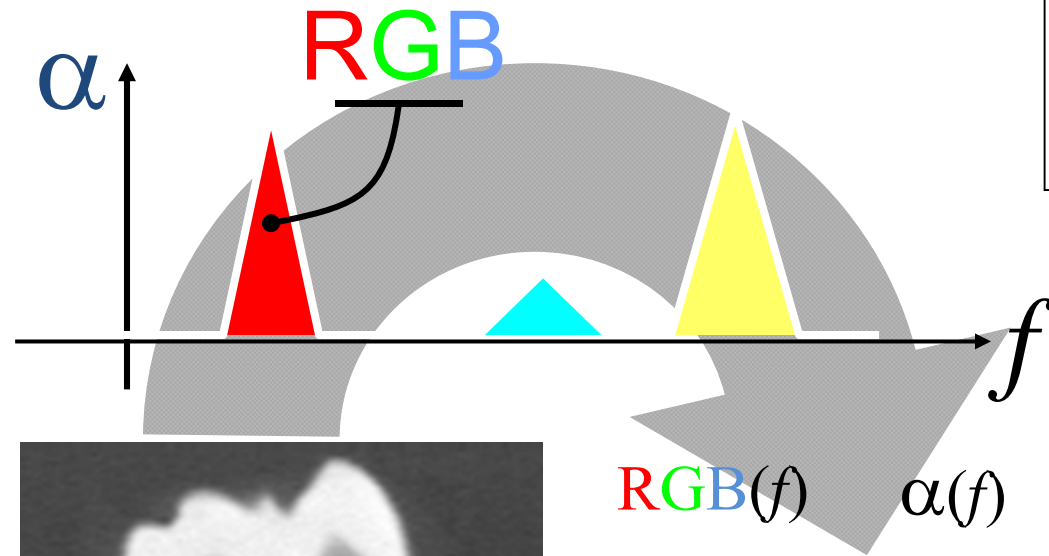
- $C(f(p)), \alpha(f(p))$  –  $p$  is a point in volume
- Functions of input data value  $f(p)$ 
  - $C(f), \alpha(f)$  – these are **1D functions**
  - Can include lighting effects
    - $C(f, N(p), \mathbf{L})$  where  $N(p) = \text{grad}(f)$
  - Derivatives of  $f$ 
    - $C(f, \text{grad}(f)), \alpha(f, \text{grad}(f))$

# Transfer Functions (TFs)

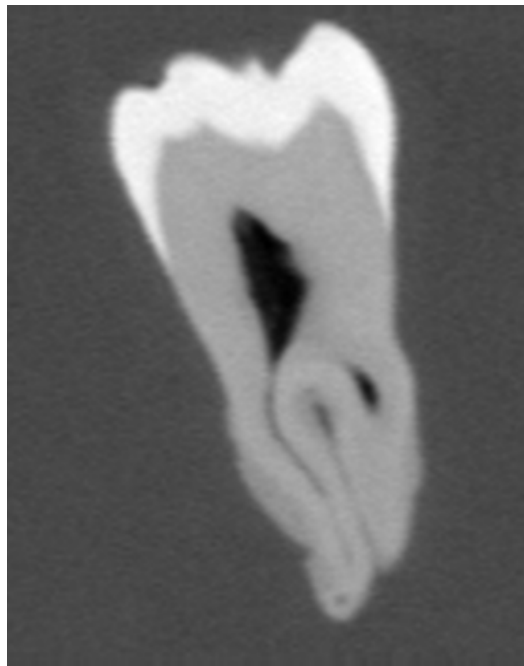
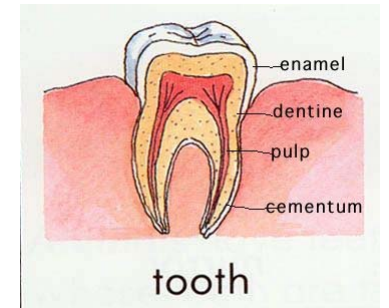


Human Tooth CT

# Transfer Functions (TFs)

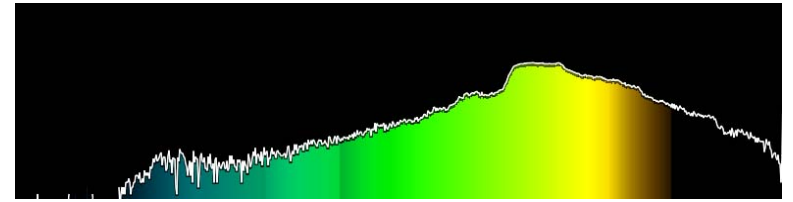


Map data value  $f$  to color and opacity

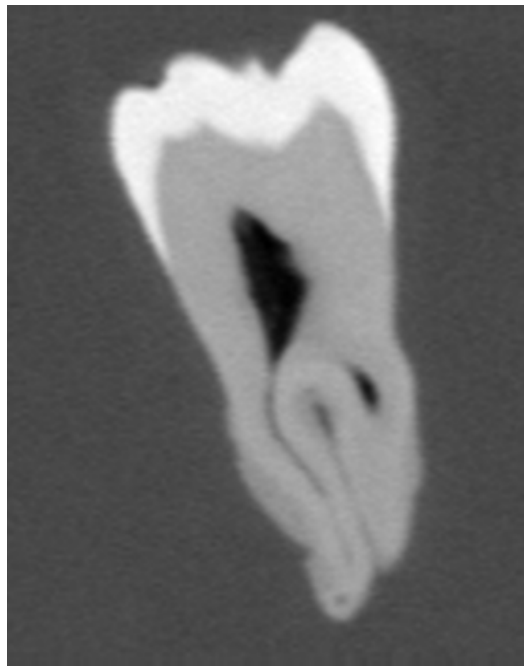
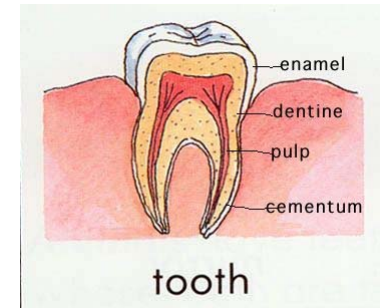
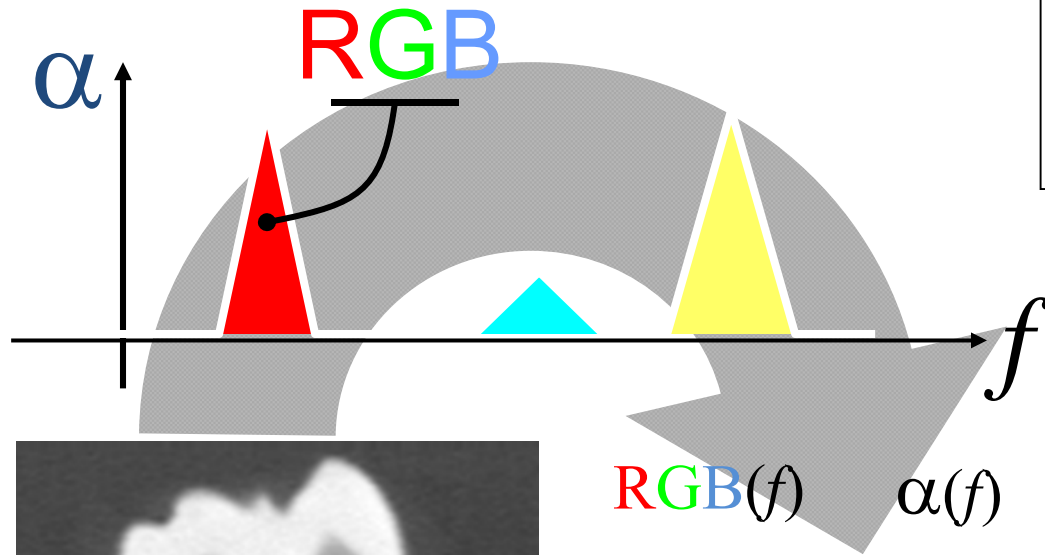


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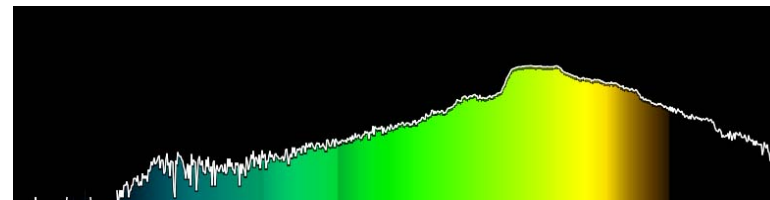


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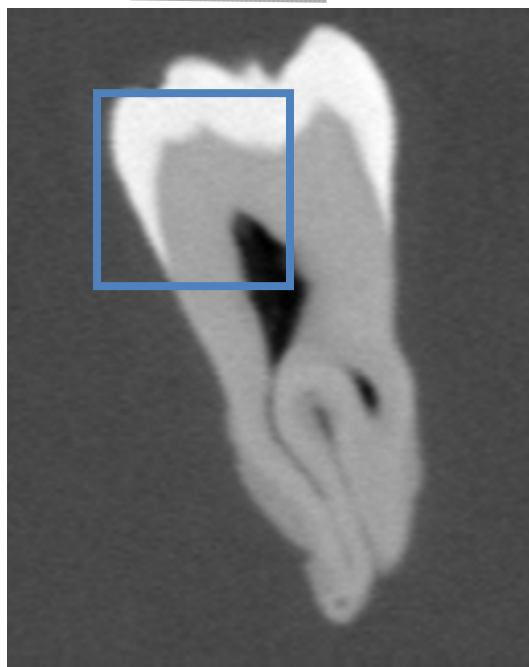
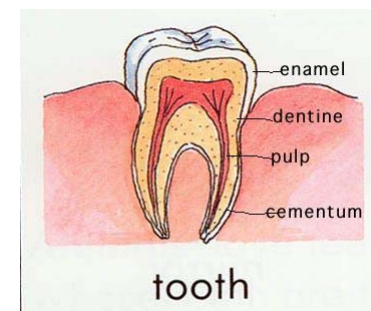
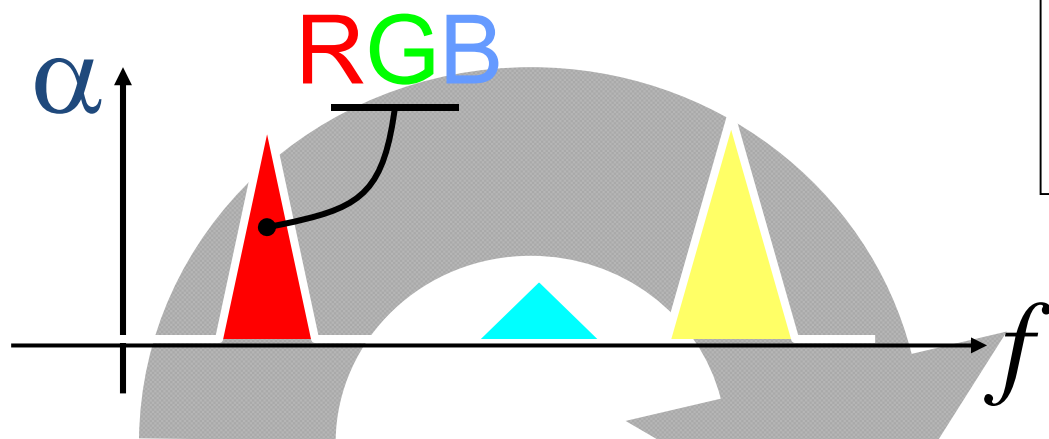


Human Tooth CT

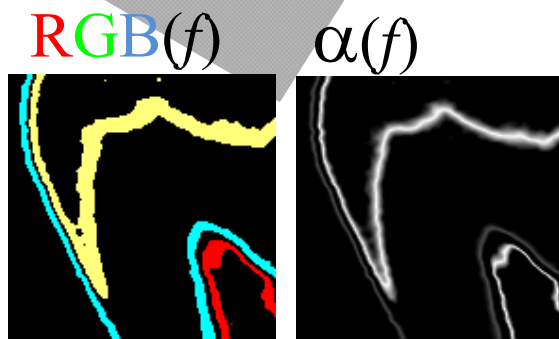
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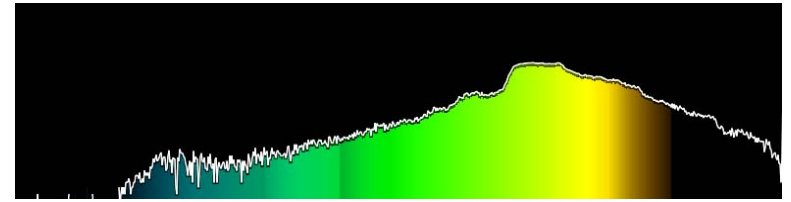
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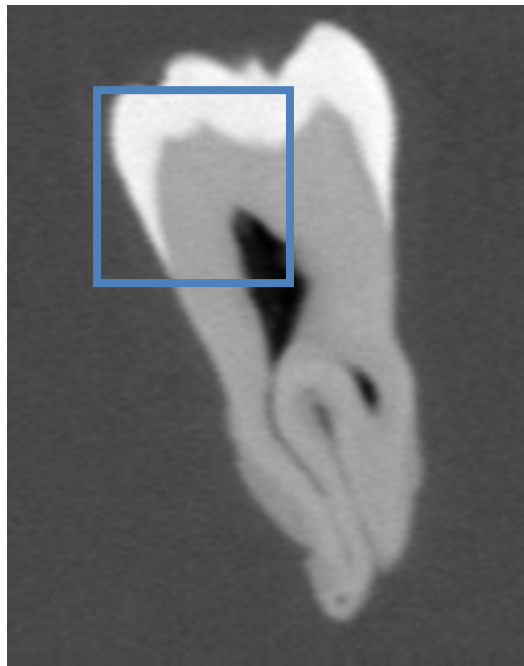
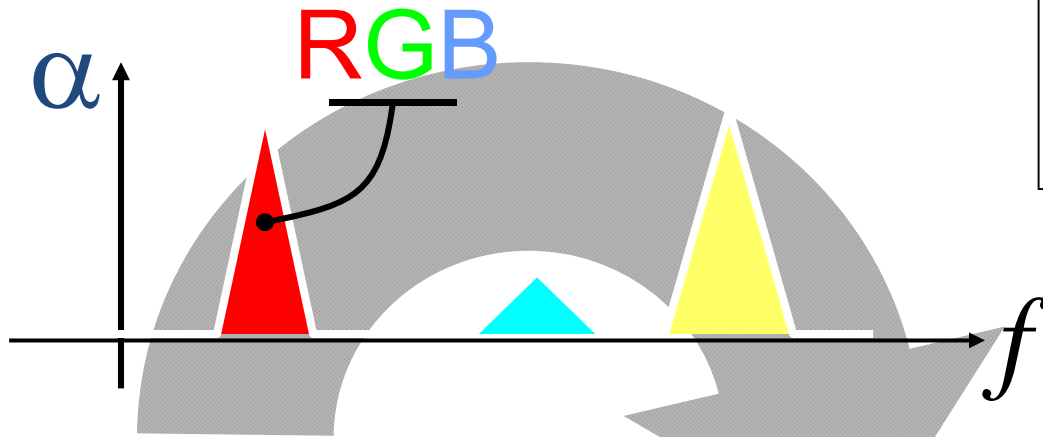
Human Tooth CT



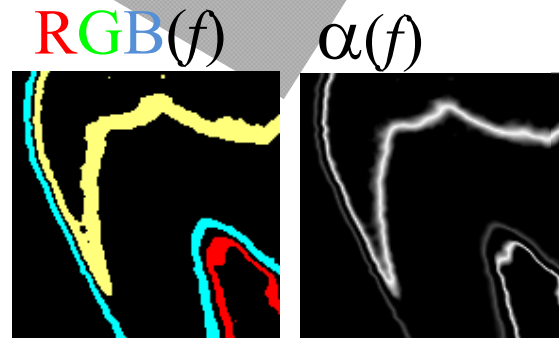
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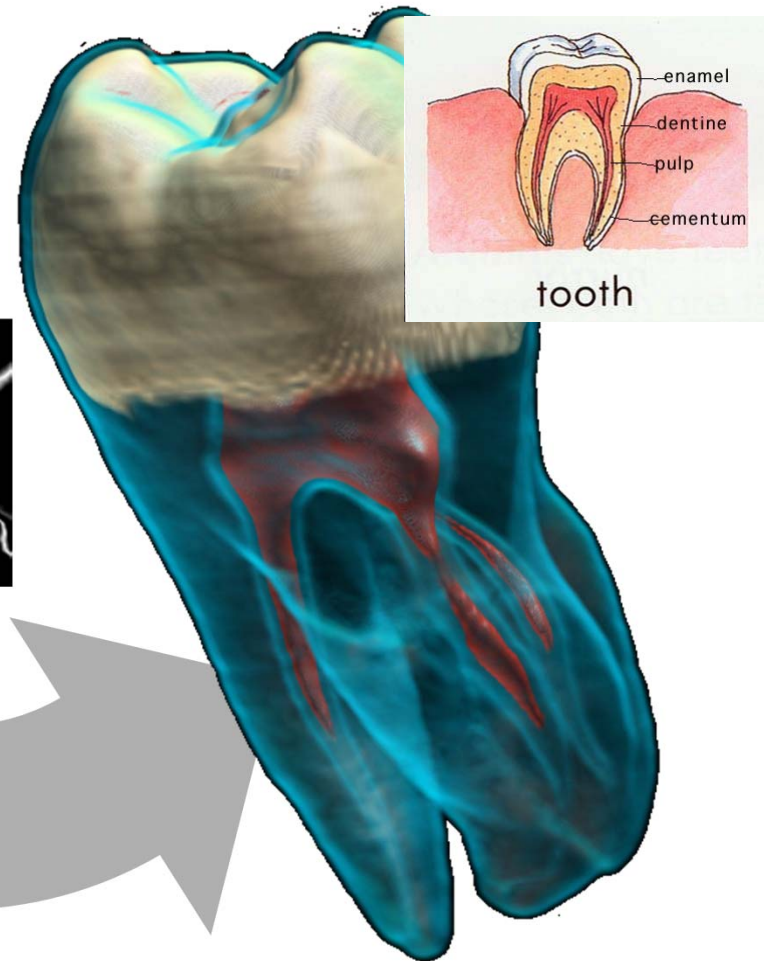
Map data value  $f$  to color and opacity



Human Tooth CT



Shading,  
Compositing...



# Gradient

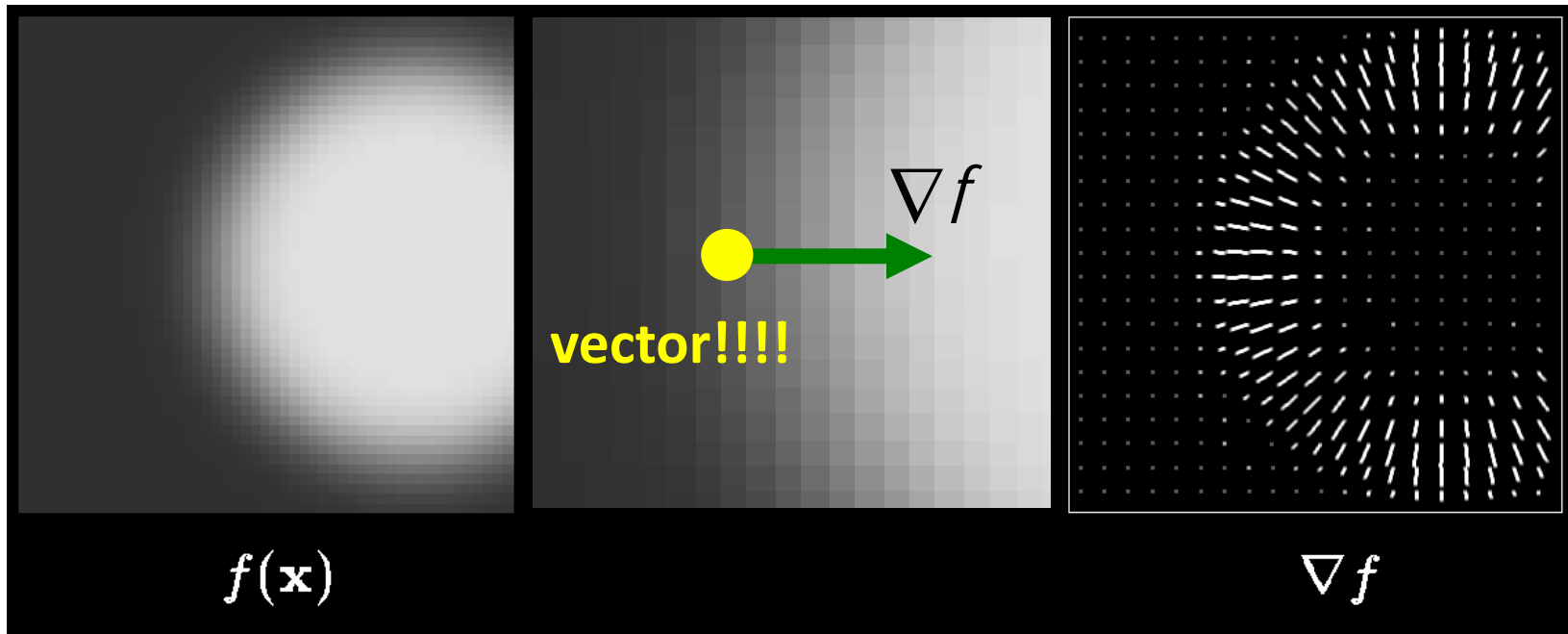
$$\begin{aligned}\nabla f &= (df/dx, df/dy, df/dz) \\ &= ( (f(1,0,0) - f(-1,0,0))/2, \\ &\quad (f(0,1,0) - f(0,-1,0))/2, \\ &\quad (f(0,0,1) - f(0,0,-1))/2 )\end{aligned}$$

Central difference

$$\frac{df}{dx} = \frac{f(x+h) - f(x-h)}{2h}$$

$$\frac{df}{dy} = \frac{f(y+h) - f(y-h)}{2h}$$

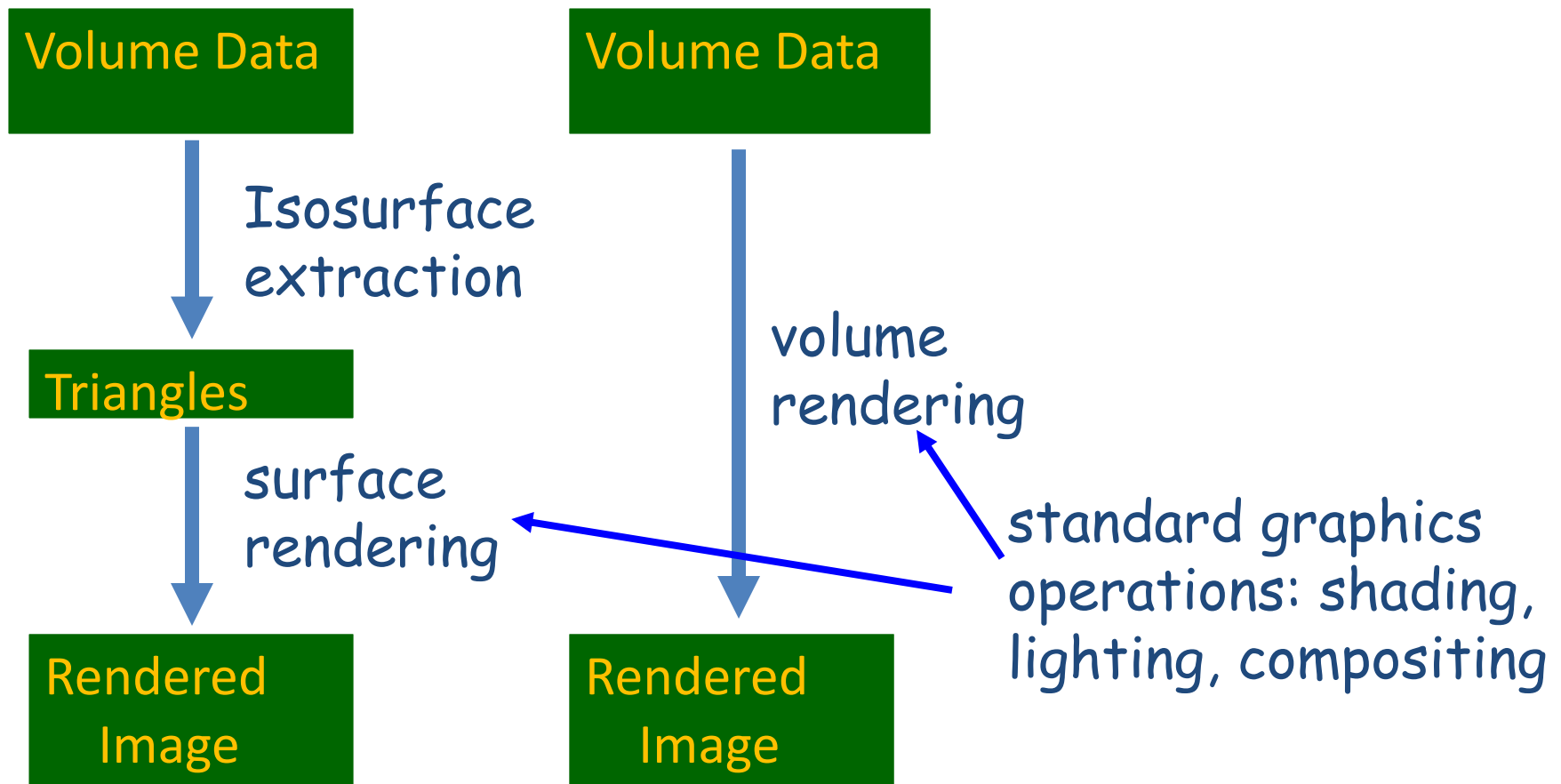
*Approximates "surface normal" (of iso-surface!)*





# Pipelines: Iso vs. Vol Ren

- The standard line - "no intermediate geometric structures"



# Computational Strategies

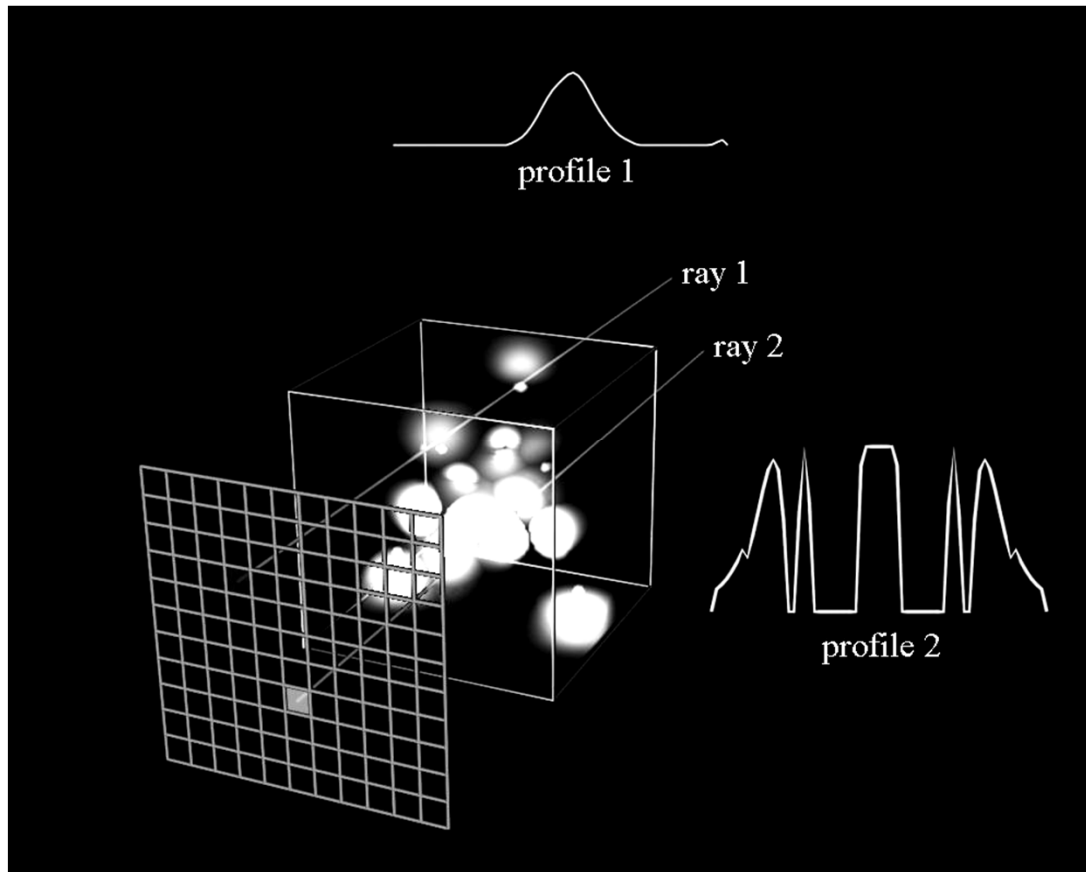
- How can the basic ingredients be combined:
  - Image Order (in screen coordinate)
    - Ray casting (many options)
  - Object Order (in world coordinate)
    - splatting, texture-mapping
  - Combination (neither)
    - Shear-warp, Fourier

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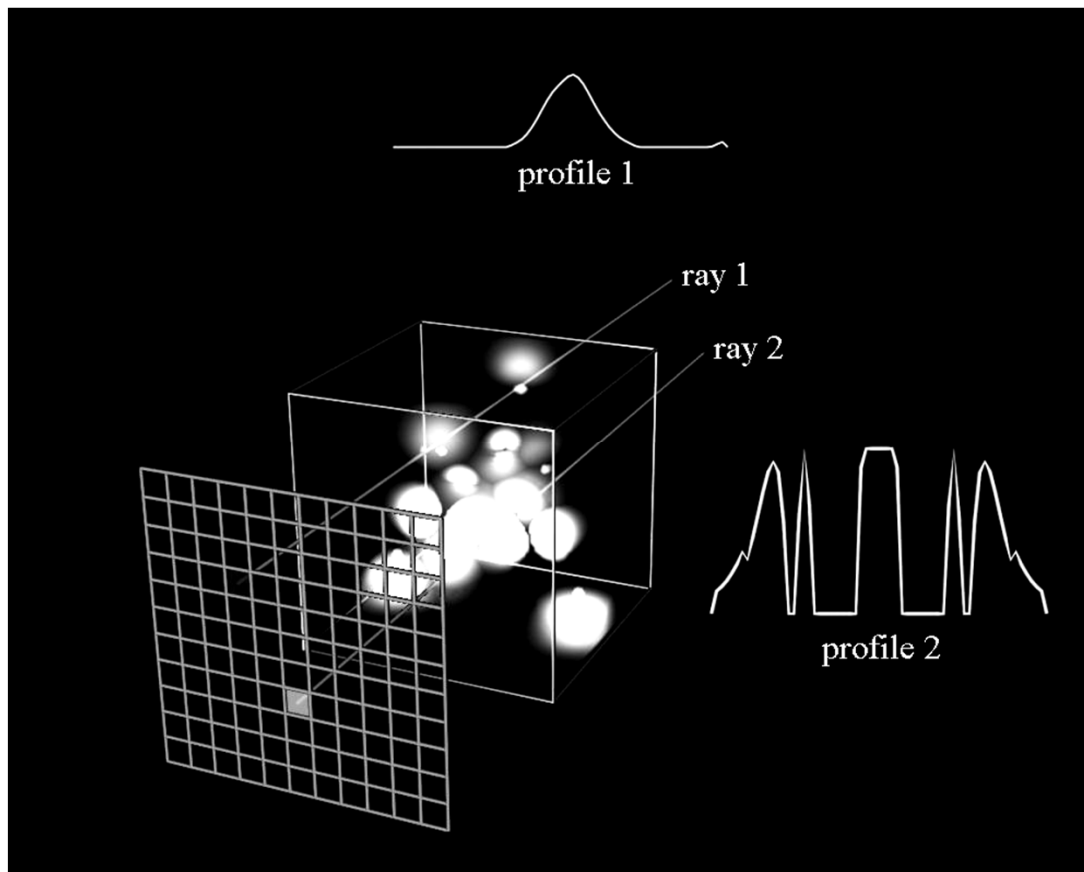
# Image Order

- Render image one pixel at a time



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For each pixel ...

- cast ray
- sampling along ray
- interpolate
- get colors/opacity
- composite

# Raycasting

- Raycasting is historically the **first volume rendering technique**.
- It shares some similarity with raytracing:
  - image-space method: main loop is over pixels of output image
  - a view ray per pixel (or per sub-pixel) is traced **backward**
  - samples are taken along the ray and composited to a single color

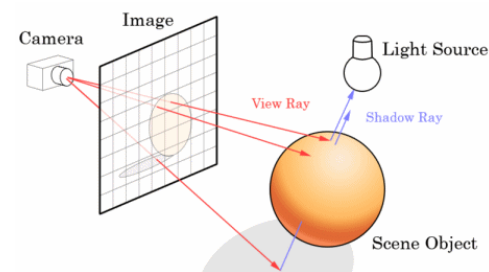
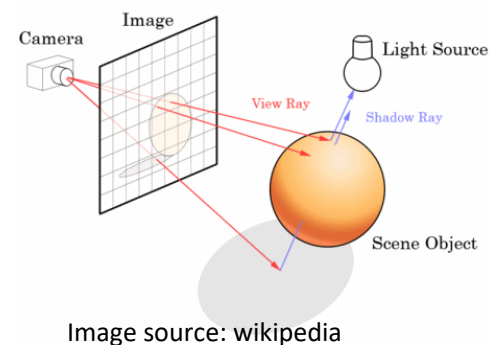


Image source: wikipedia

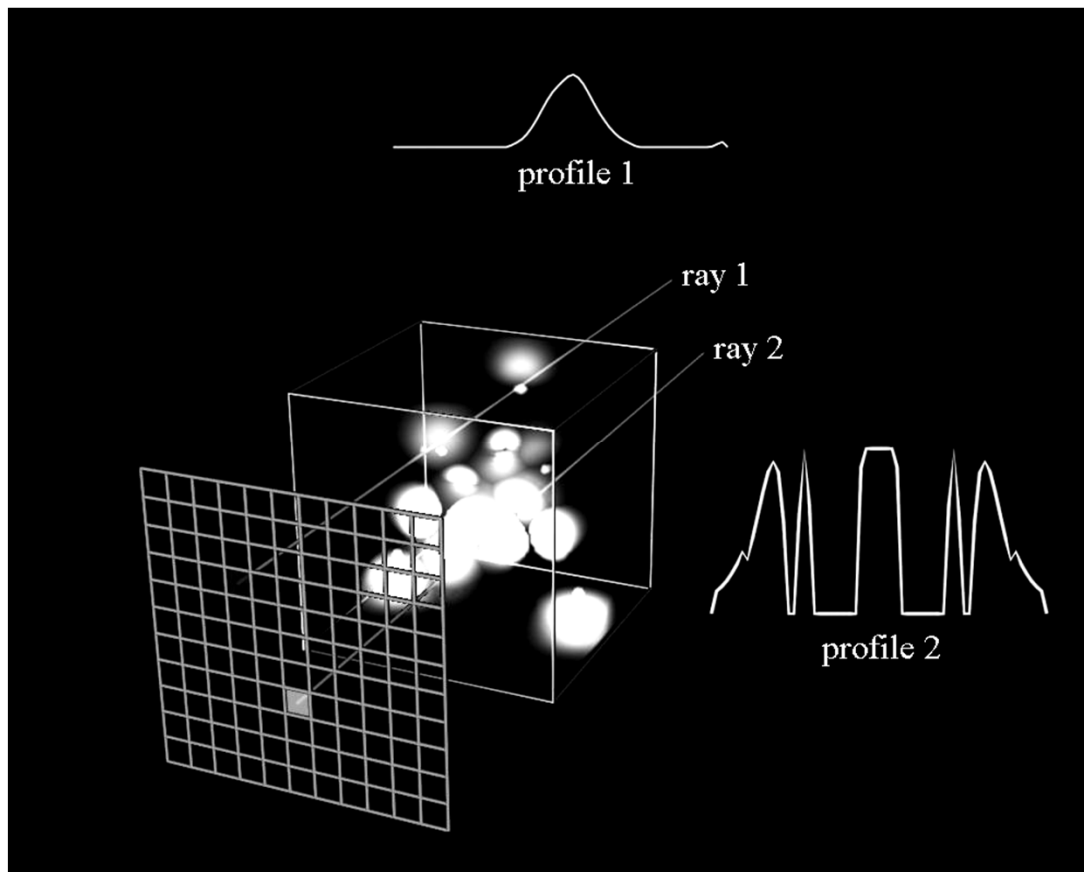
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  - image-space method: main loop is over pixels of output image
  - a view ray per pixel (or per sub-pixel) is traced **backward**
  - samples are taken along the ray and composited to a single color
- **Differences** are:
  - no secondary (reflected, shadow) rays
  - transmitted ray is not refracted
  - more elaborate compositing functions
  - samples are taken at intervals ( not at object intersections) inside volume



# Image Order

- Render image one pixel at a time



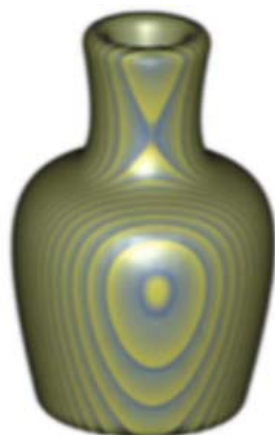
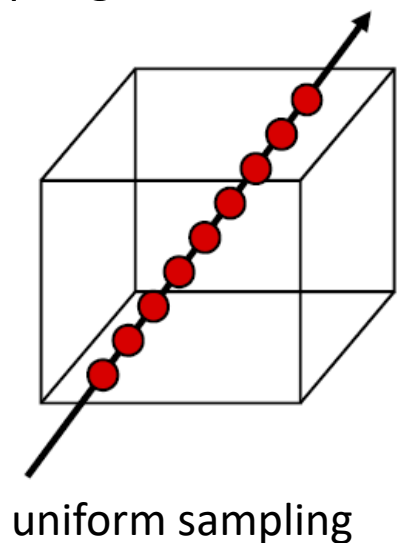
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# Raycasting

Sampling interval can be fixed or adjusted to voxels:



2.0



1.0

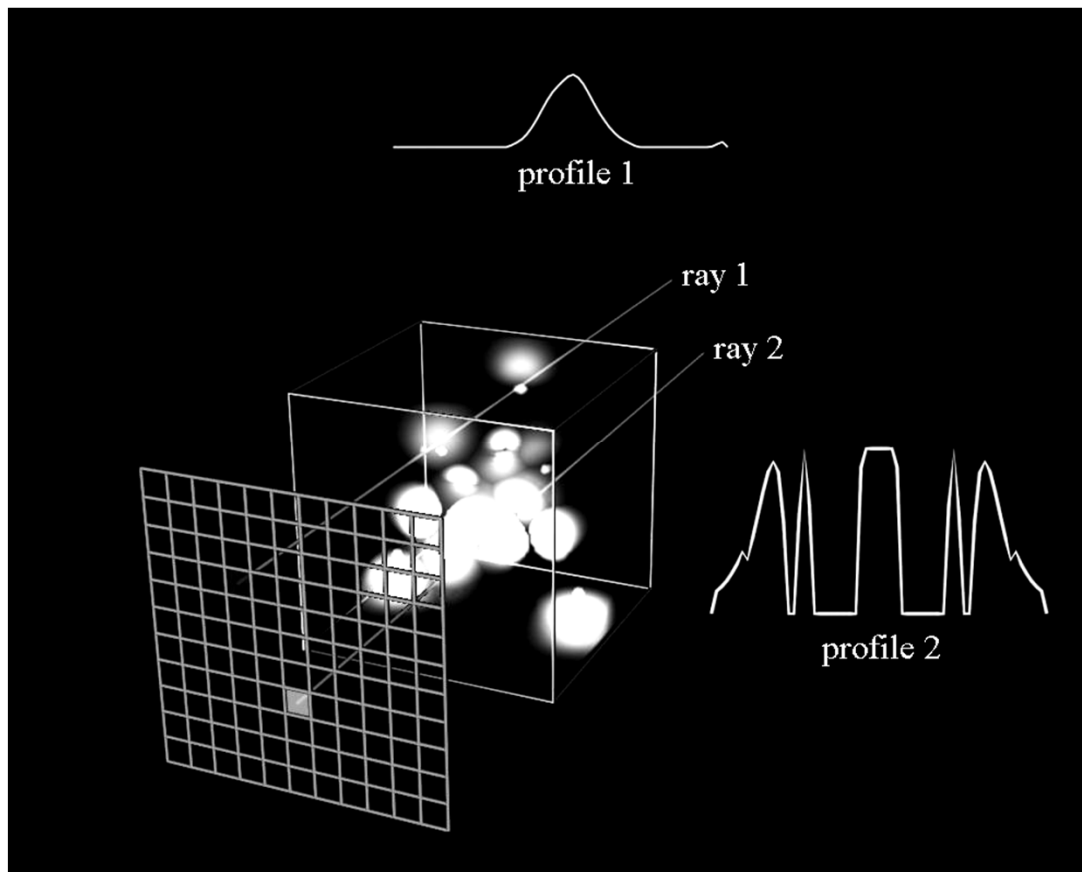


0.1

Images generated using a ray casting method with three different step sizes (or sample rate). Vase data courtesy of SUNY Stony Brook.

# Image Order

- Render image one pixel at a time

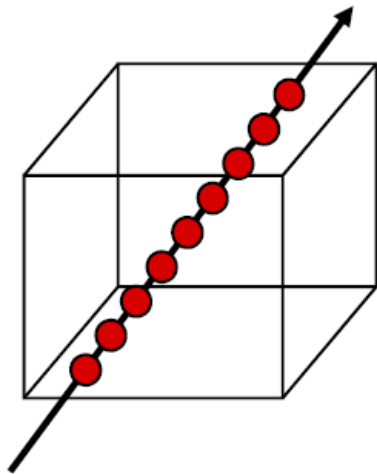


For each pixel ...

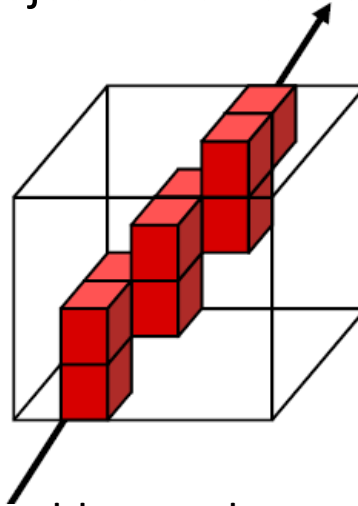
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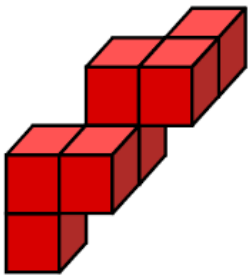


uniform sampling

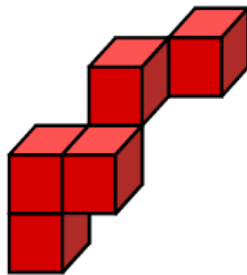


voxel-by-voxel traversal  
(faster)

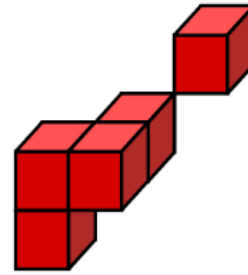
Connectedness of "voxelized" rays:



6-connected  
(strongest)



18-connected



26-connected  
(weakest)

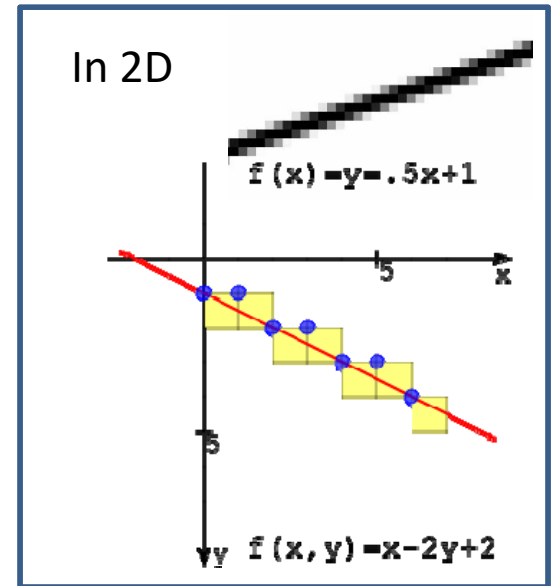
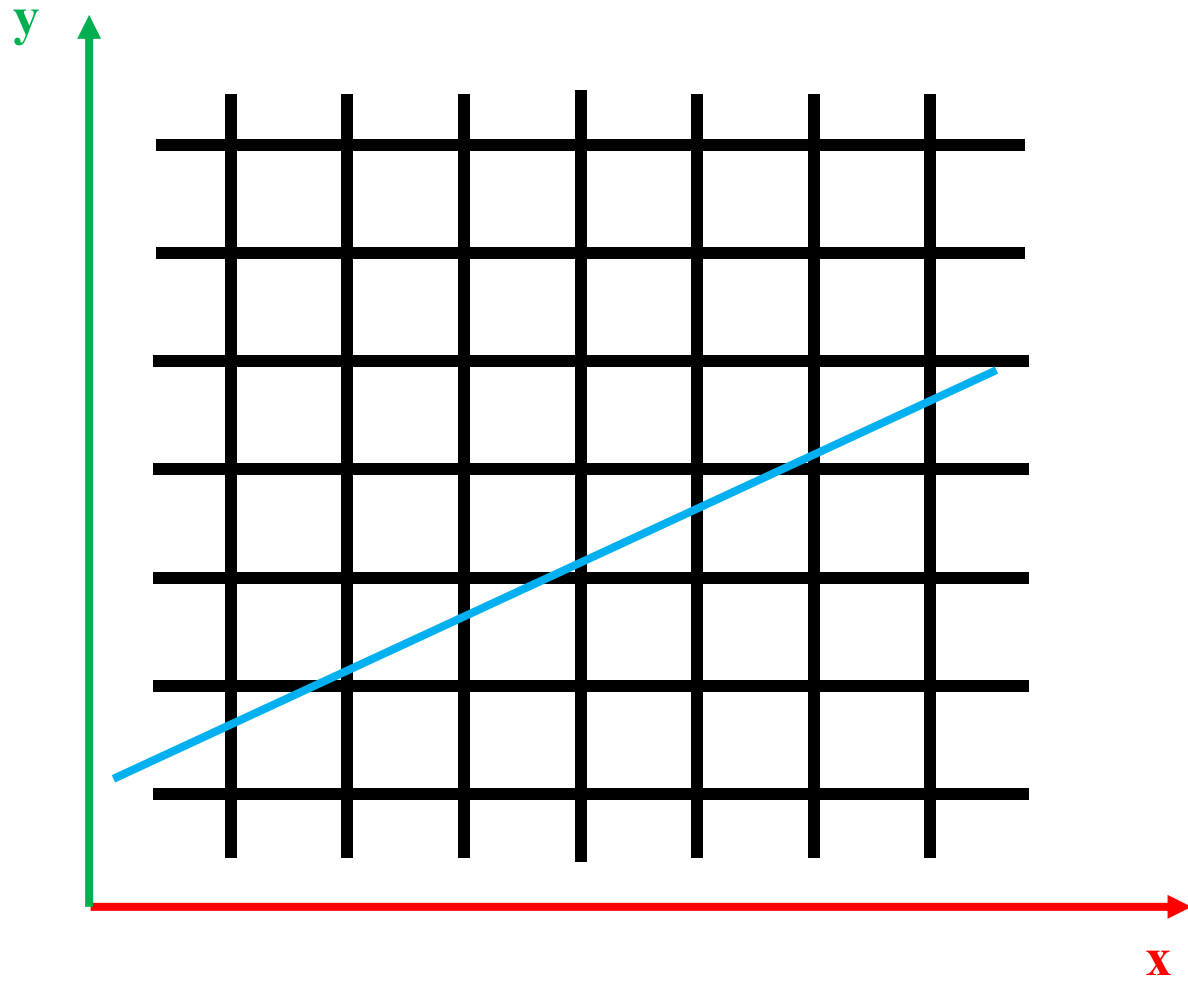


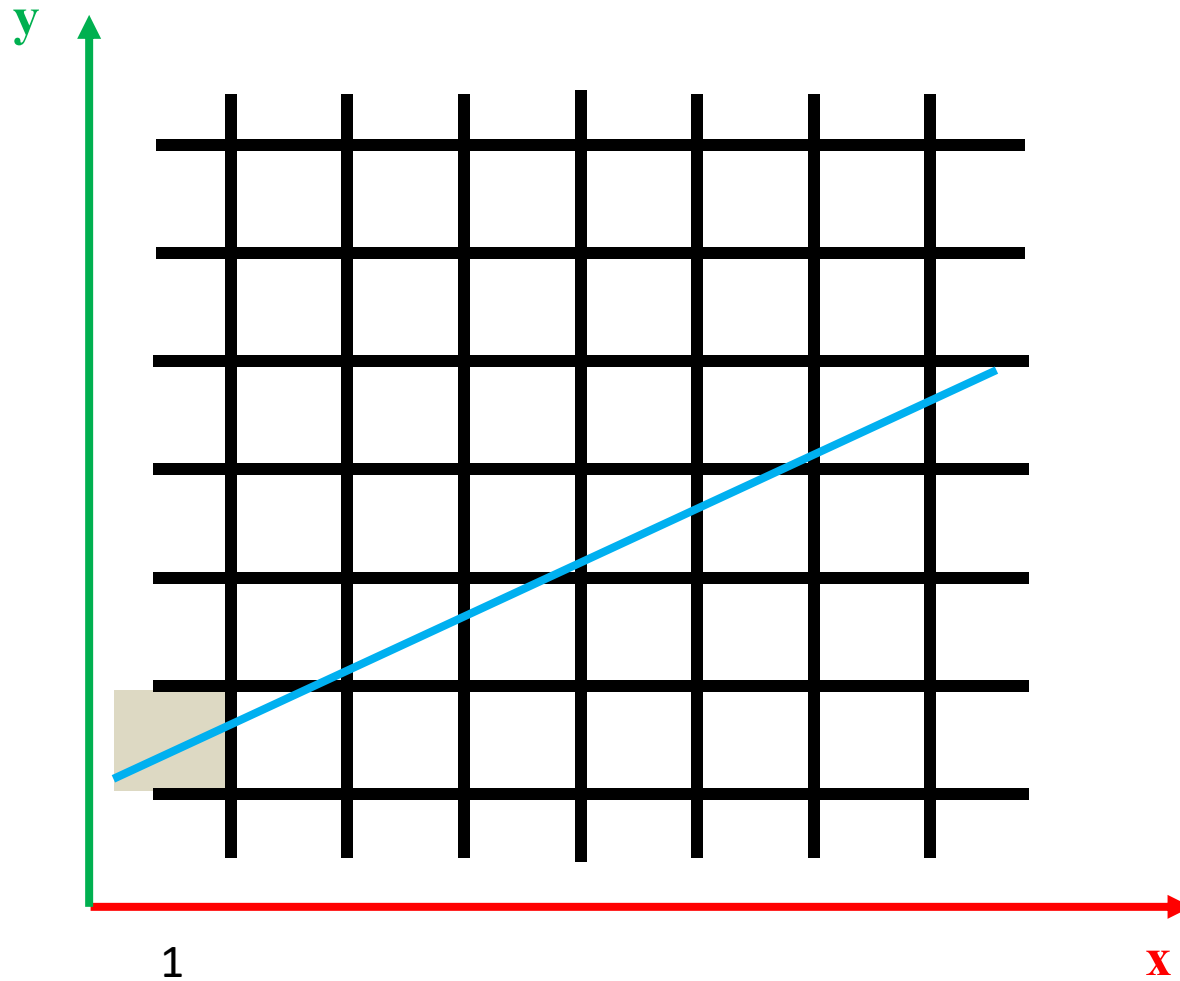
Image source: wikipedia

**Accelerate the sampling  
and interpolation**

# Line rasterization process

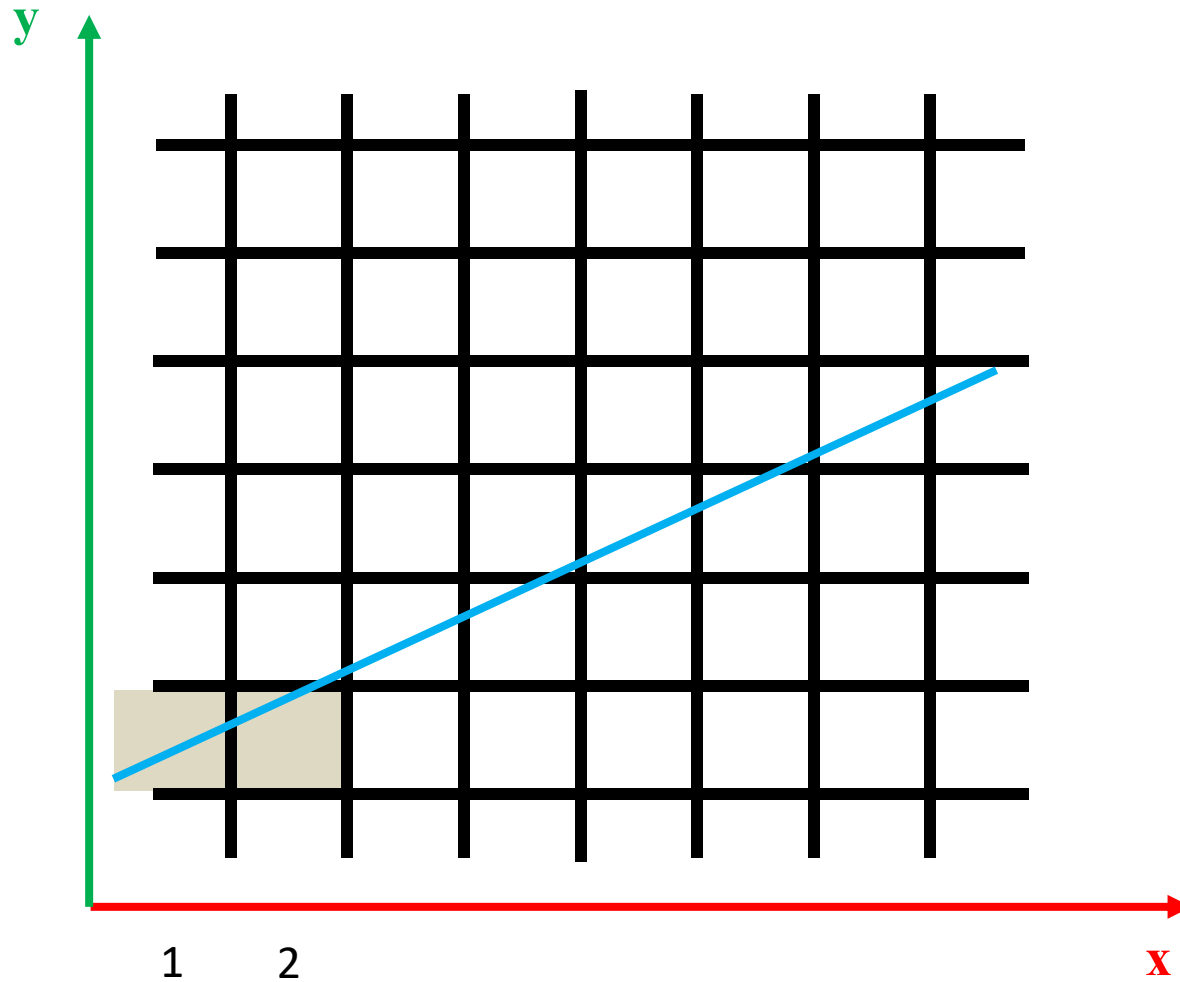


# Line rasterization process



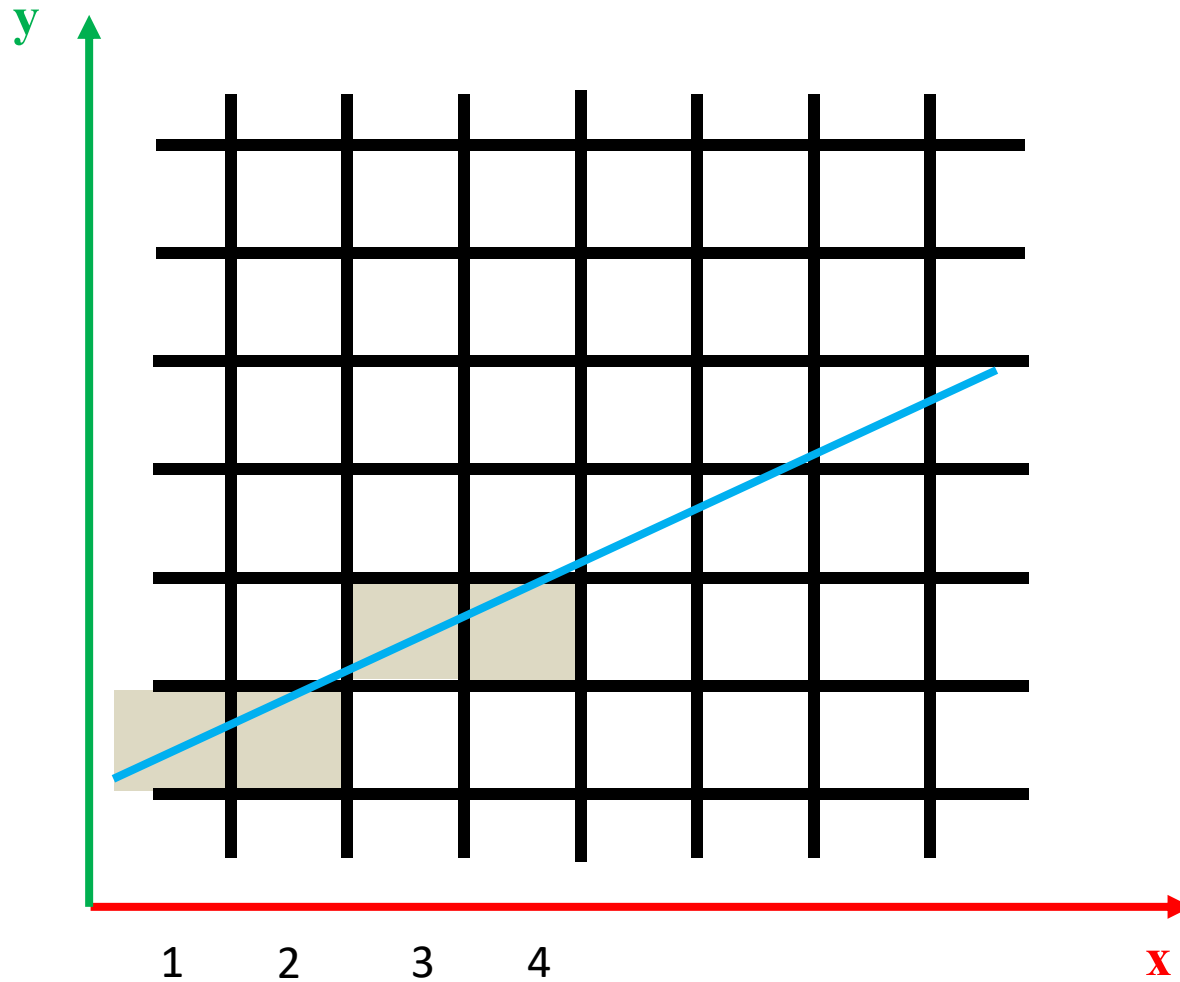
Let us increase along **x**

# Line rasterization process



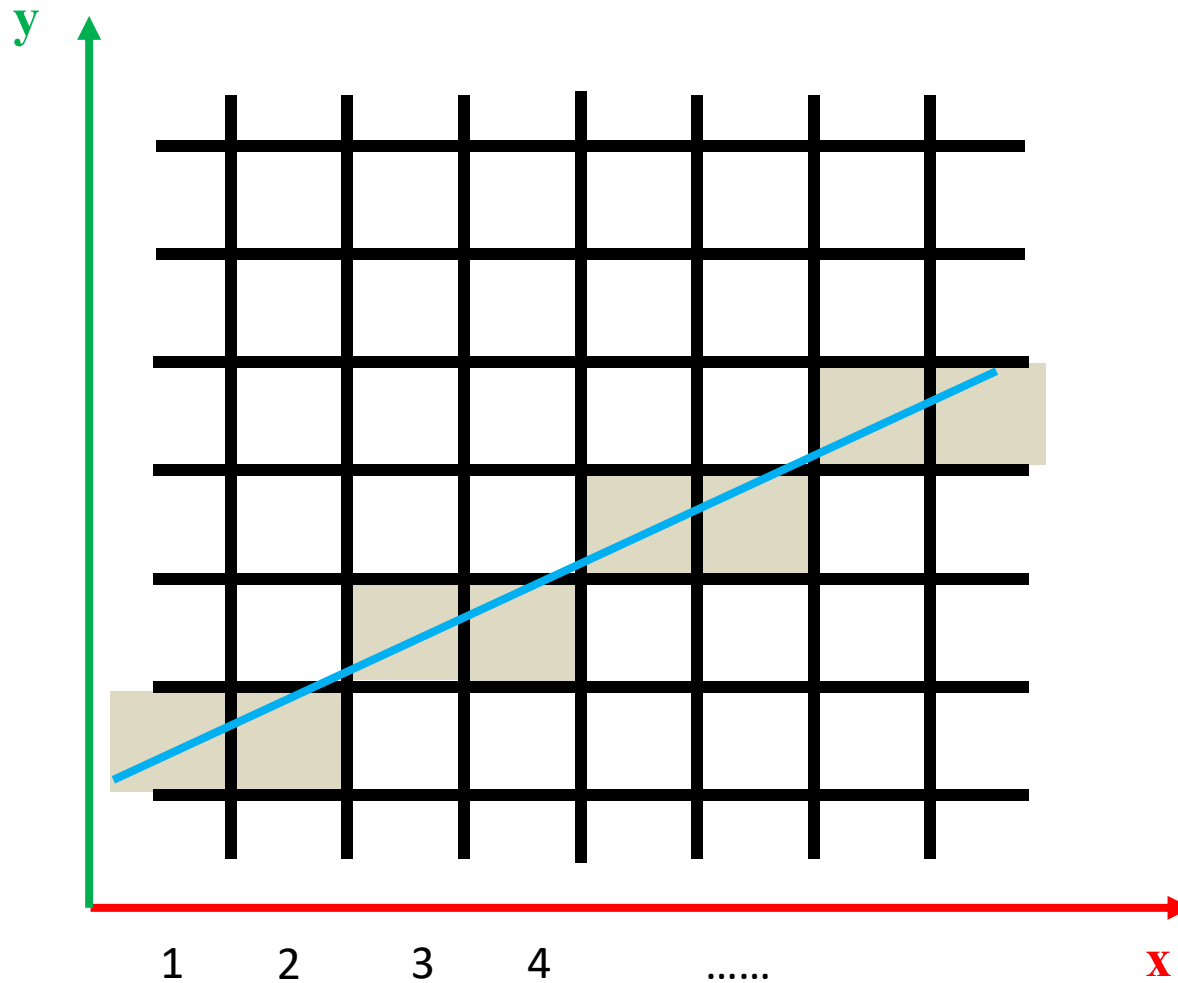
Let us increase along **x**

# Line rasterization process



Let us increase along  $x$

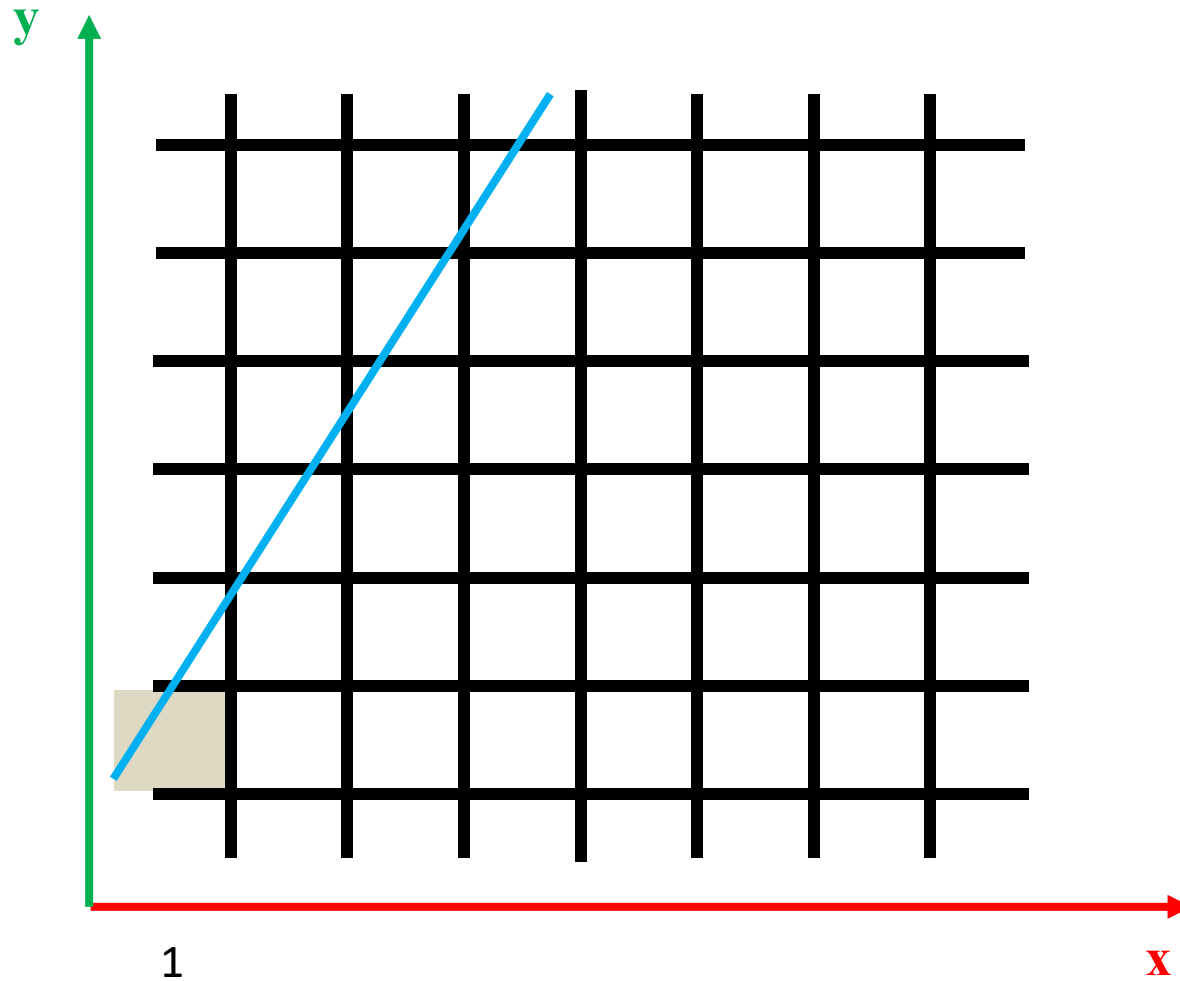
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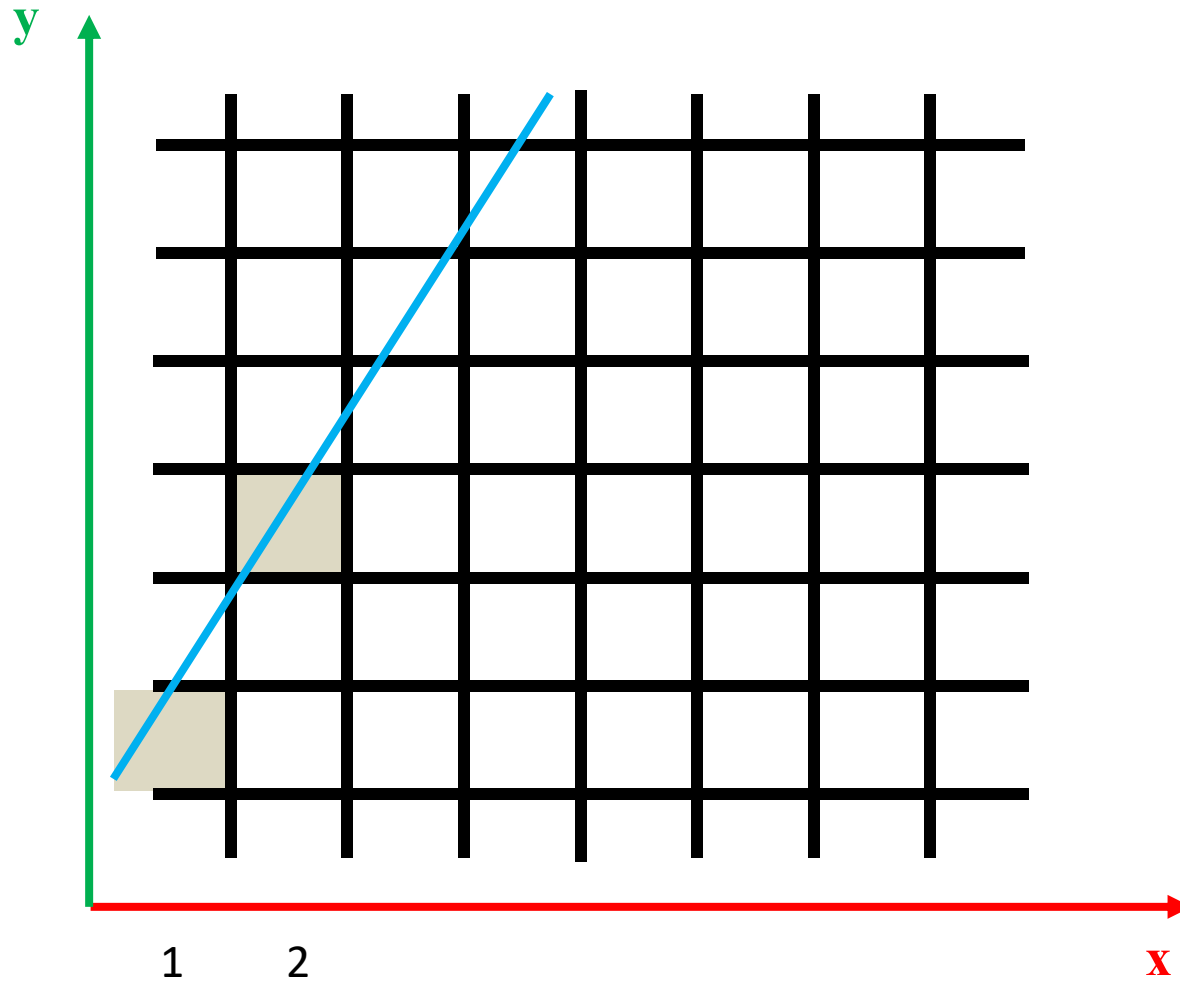


# Line rasterization process



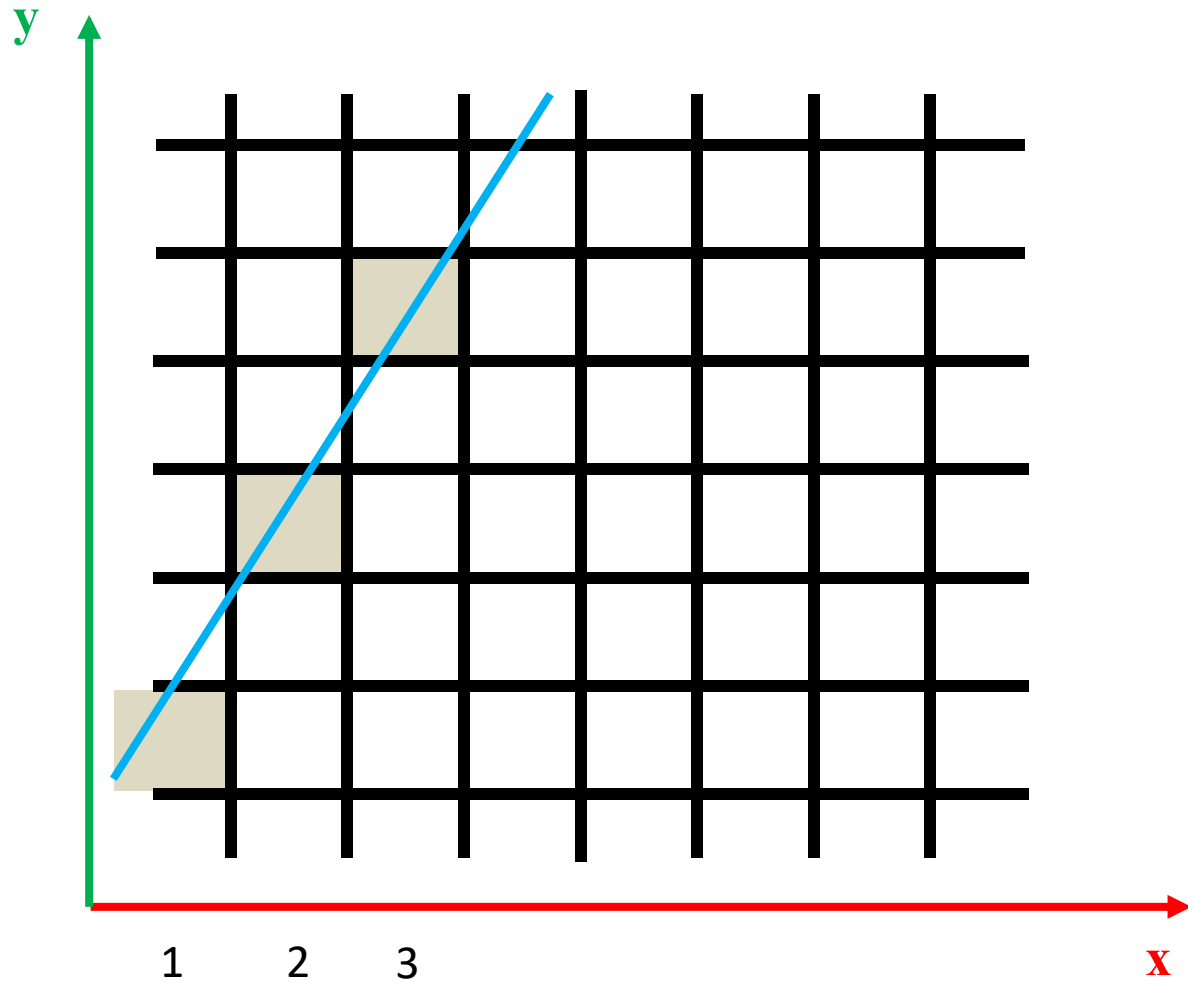
If we still increase along  $x$ , what will happen?

# Line rasterization process



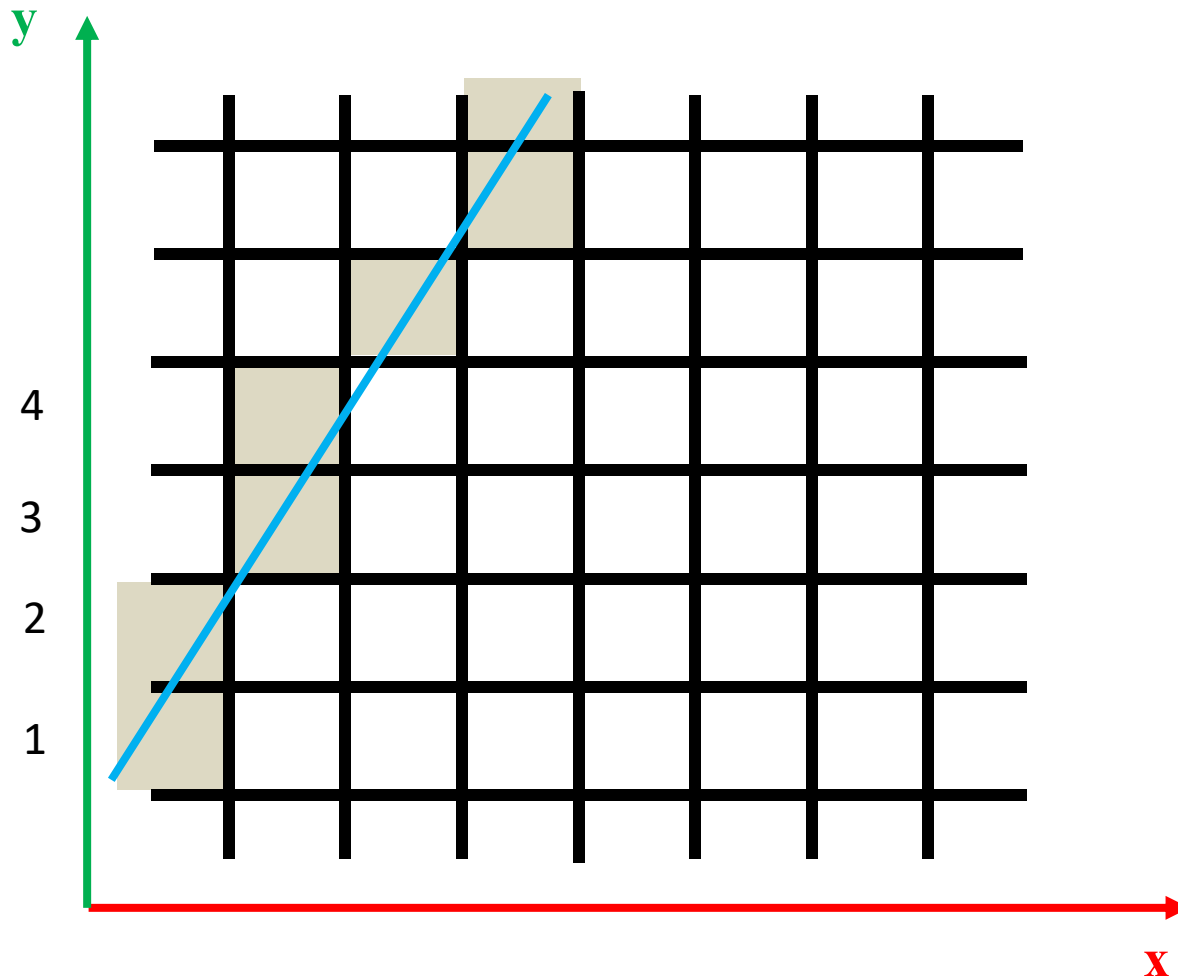
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# Line rasterization process



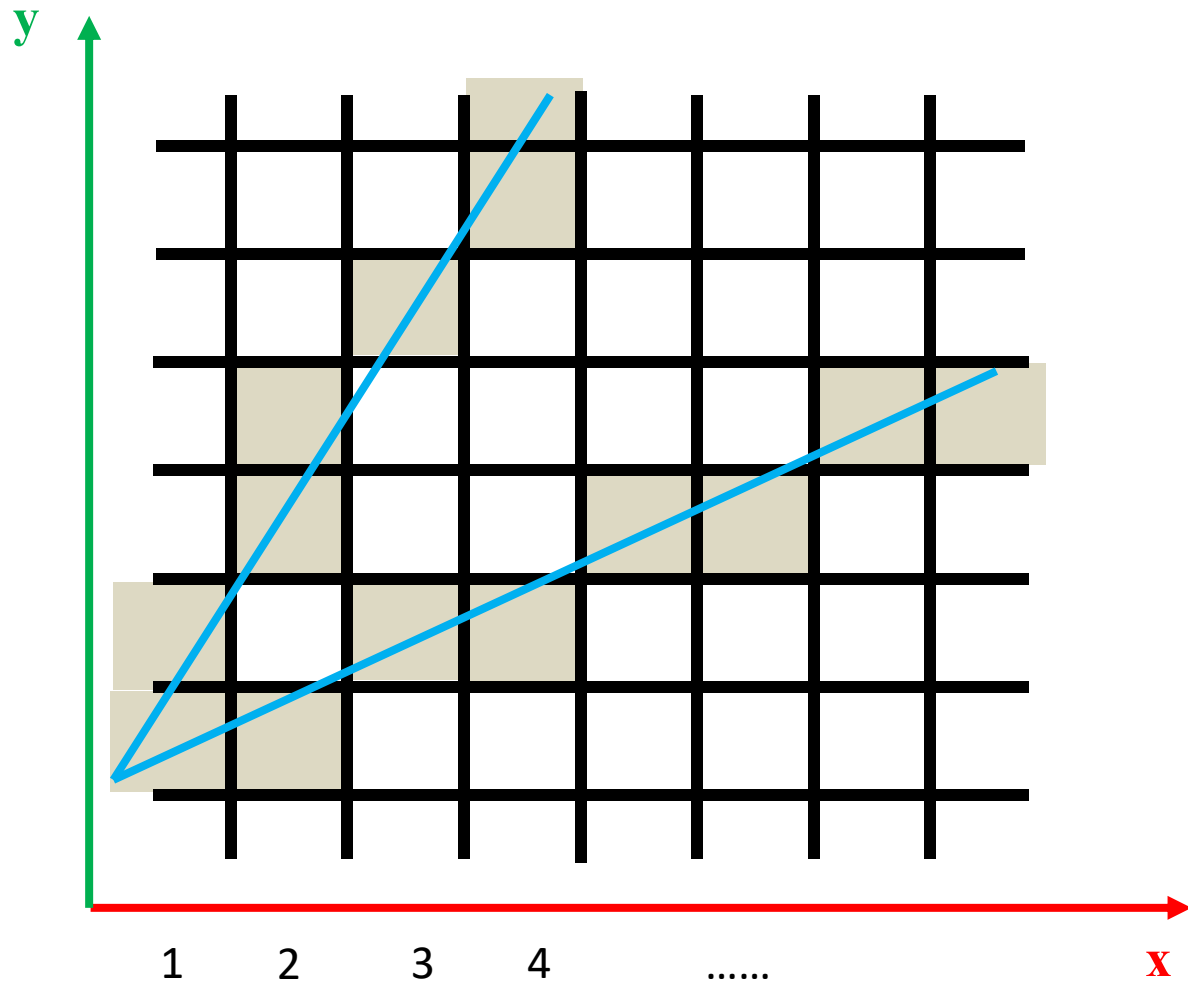
There will be many gaps between the pixels!!!

# Line rasterization process



The correct way is to increase along **y!!!**

# Line rasterization process



Lesson learned? We have to march along the axis that is most parallel to the line!

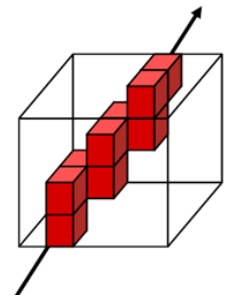
# Ray Templates

A **ray template** (Yagel 1991) is a **voxelized ray** which by translating generates all view rays.

Ray templates speed up the sampling process, but are obviously **restricted** to **orthographic** views.

## Algorithm:

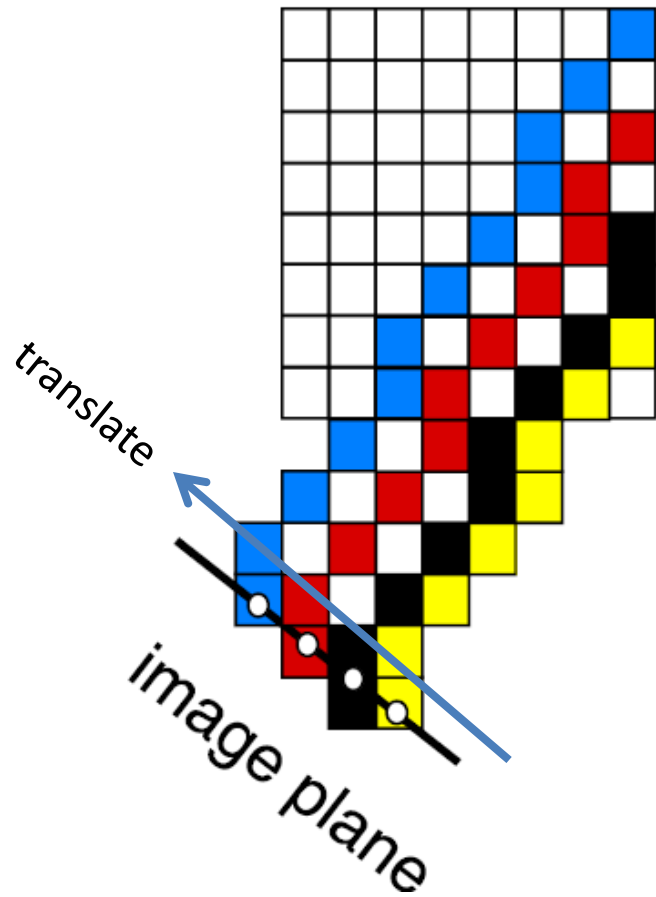
- Rename volume axes such that z is the one "most orthogonal" to the image plane (without loss of generality).
- Create ray template with 3D version of **line pixelized** algorithm, giving 26-connected rays which are functional in z coordinate (have exactly one voxel per z-layer)
- Translate ray template in **base plane**, not in image plane



**Accelerate the sampling  
and interpolation**

# Ray Templates

Incorrect: translated in image plane



Correct: translated in base plane

