## 3D Scalar Field Visualization: Volume Rendering

Goal: understand what is DVR and why it is useful; how to compute DVR (important steps); how to perform raycasting

## Iso-surfacing Could Be limited

- Iso-surfacing is "binary"
- point inside iso-surface?
- voxel contributes to image?
- Is a hard, distinct boundary necessarily appropriate for all the visualization tasks?


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Slice


Isosurface


Volume Rendering

## Iso-surfacing Could Be Limited

- Iso-surfacing poor for ...
- measured, "real-world" (noisy) data
- Amorphous (fog-like), "soft" objects

virtual angiography

bovine combustion simulation


## What is Direct Volume Rendering

- Any rendering process which maps from volume data to an image without introducing binary distinctions / intermediate geometry
- How do you make the data visible?


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- How to achieve that?


## What is Direct Volume Rendering

- Any rendering process which maps from volume data to an image without introducing binary distinctions / intermediate geometry
- How do you make the data visible? : Via Color and Opacity
- How to achieve that?
- The data is considered to represent a semi-transparent light-emitting medium
- Approaches are based on the laws of physics (emission, absorption, scattering)
- The volume data is used as a whole (look inside, see interior structures). Think of color plots in 3D!


## Volume Rendering is Useful

- Measured sources of volume data
- CT (computed tomography)
- PET (positron emission tomography)
- MRI (magnetic resonance imaging)
- Ultrasound
- Confocal Microscopy



## Volume Rendering is Useful

- Synthetic sources of volume data
- CFD (computational fluid dynamics)
- Voxelization of discrete geometry



## Data Representation

- Volume rendering techniques
- depend strongly on the grid type
- exist for both structured and unstructured grids
- are predominantly applied to uniform grids (3D images).
- for uniform grid, voxels are the basic unit


## Data Representation

- Volume rendering techniques
- depend strongly on the grid type
- exist for both structured and unstructured grids
- are predominantly applied to uniform grids (3D images).
- for uniform grid, voxels are the basic unit
- Cell-centered data for uniform grids
- are attributed to cells (pixels, voxels) rather than nodes
- can also occur in (finite volume) CFD datasets
- are converted to node data (e.g., for iso-surfacing)
- by taking the dual grid (easy for uniform grids, n cells $->\mathrm{n}-1$ cells!)
- or by interpolating.






## Important Concepts

- Interpolation
- trilinear common, others possible
- Color and opacity transfer function
- Turning scalar values to colors
- Gradient
- direction of fastest change
- Compositing
- "over operator"


## Trilinear Interpolation



This is useful, for example, if we have passed an oblique cutting plane through a 3D mesh of points and are trying to interpolate scalar values from the 3D mesh to the 2D plane.

## Color and Opacity Transfer Functions

- $C(f(p)), \boldsymbol{\alpha}(f(p))-p$ is a point in volume
- Functions of input data value $f(p)$
$-C(f), \alpha(f)$ - these are 1D functions
- Can include lighting effects
- C(f, $N(p), L)$ where $N(p)=\operatorname{grad}(f)$
- Derivatives of $f$
- C(f, grad $(f)), \alpha(f, \operatorname{grad}(f))$


## Transfer Functions (TFs)



Human Tooth CT

## Transfer Functions (TFs)


tooth

## Transfer Functions (TFs)


tooth

Human Tooth CT

## Transfer Functions (TFs)



Map data value $f$ to color and opacity


tooth

Human Tooth CT

## Transfer Functions (TFs)




Map data value $f$ to color

Shading,
Compositing...
Human Tooth CT


tooth

## Gradient

$$
\begin{gathered}
\nabla \mathrm{f}=(\mathrm{df} / \mathrm{dx}, \mathrm{df} / \mathrm{dy}, \mathrm{df} / \mathrm{dz}) \\
=((\mathrm{f}(1,0,0)-\mathrm{f}(-1,0,0)) / 2, \\
(\mathrm{f}(0,1,0)-\mathrm{f}(0,-1,0)) / 2, \\
(\mathrm{f}(0,0,1)-\mathrm{f}(0,0,-1)) / 2)
\end{gathered}
$$

Central difference

$$
\begin{aligned}
& \frac{d f}{d x}=\frac{f(x+h)-f(x-h)}{2 h} \\
& \frac{d f}{d y}=\frac{f(y+h)-f(y-h)}{2 h}
\end{aligned}
$$

Approximates "surface normal" (of iso-surface!)


## Pipelines: Iso vs. Vol Ren

- The standard line - "no intermediate geometric structures"



## Computational Strategies

- How can the basic ingredients be combined:
- Image Order (in screen coordinate)
- Ray casting (many options)
- Object Order (in world coordinate)
- splatting, texture-mapping
- Combination (neither)
- Shear-warp, Fourier


## Computational Strategies

- How can the basic ingredients be combined:
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## Image Order

- Render image one pixel at a time

ray 1



## Image Order

- Render image one pixel at a time

ray 1
ray 2

profile 2
For each pixel ...
- cast ray
- sampling along ray
- interpolate
- get colors/opacity
- composite


## Raycastine

- Raycasting is historically the first volume rendering technique.
- It shares some similarity with raytracing:
- image-space method: main loop is over pixels of output image
- a view ray per pixel (or per sub-pixel) is traced backward
- samples are taken along the ray and composited to a single color


Image source: wikipedia

## Raycastine

- Raycasting is historically the first volume rendering technique.
- It shares some similarity with raytracing:
- image-space method: main loop is over pixels of output image
- a view ray per pixel (or per sub-pixel) is traced backward
- samples are taken along the ray and composited to a single color
- Differences are:
- no secondary (reflected, shadow) rays
- transmitted ray is not refracted
- more elaborate compositing functions
- samples are taken at intervals ( not at object intersections) inside volume



## Image Order

- Render image one pixel at a time


For each pixel ...

- cast ray
- sampling along ray
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## Raycasting

Sampling interval can be fixed or adjusted to voxels:

uniform sampling

2.0

1.0

0.1

Images generated using a ray casting method with three different step sizes (or sample rate).
Vase data courtesy of SUNY Stony Brook.

## Image Order

- Render image one pixel at a time

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## Raycasting

Sampling interval can be fixed or adjusted to voxels:


Connectedness of "voxelized" rays:


6-connected (strongest)


18-connected


26-connected (weakest)


Accelerate the sampling and interpolation

Line rasterization process


Line rasterization process


Line rasterization process


Line rasterization process


Line rasterization process


Line rasterization process


If we still increase along $x$, what will happen?

Line rasterization process


If we still increase along $x$, what will happen?

Line rasterization process


There will be many gaps between the pixels!!!

Line rasterization process


The correct way is to increase along y!!!

## Line rasterization process



Lesson learned? We have to march along the axis that is most parallel to the line!

## Ray Templates

A ray template (Yagel 1991) is a voxelized ray which by translating generates all view rays.
Ray templates speed up the sampling process, but are obviously restricted to orthographic views.

Algorithm:

- Rename volume axes such that z is the one "most orthogonal" to the image plane (without loss of generality).
- Create ray template with 3D version of line pixelized algorithm, giving 26connected rays which are functional in z coordinate (have exactly one voxel per z-layer)
- Translate ray template in base plane, not in image plane

Accelerate the sampling and interpolation

## Ray Templates

Incorrect: translated in image plane

Correct: translated in base plane


## Image Order

- Render image one pixel at a time


For each pixel ...

- cast ray
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Important topic for the later

## Image Order

- Render image one pixel at a time

ray 1
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For each pixel ...
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## Compositing

Two simple compositing functions can be used for previewing:

- Maximum intensity projection (MIP):
- maximum of sampled values
- result resembles X-ray image


Source: wikipedia

## Compositing

Two simple compositing functions can be used for previewing:

- Maximum intensity projection (MIP):
- maximum of sampled values
- result resembles X-ray image
- Local maximum intensity projection (LMIP):
- first local maximum which is above a prescribed threshold
- approximates occlusion
- faster \& better(!)



## Compositing

Comparison of techniques (Y. Sato, dataset of a left kidney): Iso-surface vs. raycasting with MIP, LMIP, $\boldsymbol{\alpha}$-compositing
fast
(1 parameter)
-
lighting
occlusion (transparency)

fast
parameter free full data range noise insensitive

## Compositing

Comparison of techniques (Y. Sato, dataset of a left kidney): Iso-surface vs. raycasting with MIP, LMIP, $\alpha$-compositing

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(1 parameter)
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occlusion (transparency) -

fast
parameter free full data range noise insensitive

-     - 
- (occlusion)

fast
(1 parameter) full data range noise insensitive
- 
- 


-
-
full data range noise insensitive lighting occlusion transparency

## $\alpha$-compositing

Assume that each sample on a view ray has color and opacity:

$$
\left(C_{0}, \alpha_{0}\right), \cdots,\left(C_{N}, \alpha_{N}\right) \quad C_{i} \in[0,1]^{3}, \alpha_{i} \in[0,1]
$$

where the $0^{\text {th }}$ sample is next to the camera and the $\mathrm{N}^{\text {th }}$ one is a (fully opaque) background sample:

$$
\begin{aligned}
& C_{N}=(r, g, b)_{\text {background }} \\
& \alpha_{N}=1
\end{aligned}
$$



## $\alpha$-compositing

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& \alpha_{N}=1
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$$

$\alpha$-compositing can be defined recursively:
Let $C_{f}^{b}$ denote the composite color of samples $f, f+1, \ldots, b$
Recursion formula for back-to-front compositing:


$$
C_{b}^{b}=\alpha_{b} C_{b} \quad \text { background color and opacity }
$$

Composite color of $C^{b}=a^{b}$ Composite color of the the current iteration
Composite opacity $\longrightarrow \alpha_{f}^{b}=\alpha_{f}+\left(1-\alpha_{f}\right) \alpha_{f+1}{ }^{b}$

## $\alpha$-compositing

The first few generations, written with transparency $T_{i}=1-\alpha_{i}$

$$
\begin{aligned}
& C_{b}^{b}=\alpha_{b} C_{b} \\
& C_{b-1}^{b}=\alpha_{b-1} C_{b-1}+\alpha_{b} C_{b} T_{b-1} \\
& C_{b-2}^{b}=\alpha_{b-2} C_{b-2}+\alpha_{b-1} C_{b-1} T_{b-2}+\alpha_{b} C_{b} T_{b-1} T_{b-2} \\
& C_{b-3}^{b}=\alpha_{b-3} C_{b-3}+\alpha_{b-2} C_{b-2} T_{b-3}+\alpha_{b-1} C_{b-1} T_{b-2} T_{b-3}+\alpha_{b} C_{b} T_{b-1} T_{b-2} T_{b-3}
\end{aligned}
$$

reveal the closed formula for $\alpha$-compositing:

$$
C_{f}^{b}=\sum_{i=f}^{b} \alpha_{i} C_{i} \prod_{j=f}^{i-1} T_{j}
$$

## $\alpha$-compositing

front-to-back compositing can be derived from the closed formula:
Let $T_{f}^{b}$ denote the composite transparency of samples $f, f+1, \ldots, b$

$$
T_{f}^{b}=\prod_{j=f}^{b} T_{j}
$$

Then the simultaneous recursion for front-to-back compositing is:


$$
\begin{aligned}
C_{f}^{f} & =\alpha_{f} C_{f} \\
T_{f}^{f} & =1-\alpha_{f} \\
C_{f}^{b+1} & =C_{f}^{b}+\alpha_{b+1} C_{b+1} T_{f}^{b} \\
T_{f}^{b+1} & =\left(1-\alpha_{b+1}\right) T_{f}^{b}
\end{aligned}
$$

## $\alpha$-compositing

front-to-back compositing can be derived from the closed formula:
Let $T_{f}^{b}$ denote the composite transparency of samples $f, f+1, \ldots, b$

$$
T_{f}^{b}=\prod_{j=f}^{b} T_{j}
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Then the simultaneous recursion for front-to-back compositing is:


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C_{f}^{f} & =\alpha_{f} C_{f} \\
T_{f}^{f} & =1-\alpha_{f} \\
C_{f}^{b+1} & =C_{f}^{b}+\alpha_{b+1} C_{b+1} T_{f}^{b} \\
T_{f}^{b+1} & =\left(1-\alpha_{b+1}\right) T_{f}^{b}
\end{aligned}
$$

Advantage of front-to-back compositing: early ray termination when composite transparency falls below a threshold.

## Compositing Example I



## Compositing Example I



## Compositing Example II

$C_{f}=(0,1,1)$
$a_{f}=0.4$
Coseres)
$C_{b}=(1,0,0)$
$a_{b}=0.9$
$\angle C_{f}=(0,1,0)$
$a_{f}=0.4$
$c_{\text {red }}=0.4 * 0+(1-0.4) \star 0.9 * 1=0.6 * 0.9=0.54$
$c_{\text {green }}=0.4^{\star} 1+(1-0.4)^{\star} 0.9^{\star} 0=0.4$
$c_{\text {blue }}=0.4^{\star} 0+(1-0.4)^{\star} 0.9^{\star} 0=0$
$a=0.4+(1-0.4) *(0.9)=0.4+0.6 * 0.9)$
$c_{b}=(0.54,0.4,0)$
$a_{b}=0.94$
$\mathrm{c}=\mathrm{a}_{\mathrm{f}} * \mathrm{Cff}_{\mathrm{f}}+\left(1-\mathrm{a}_{\mathrm{f}}\right) * \mathrm{ab}_{\mathrm{b}} * \mathrm{Cb}_{\mathrm{b}}$
$a=a_{f}+\left(1-a_{f}\right) * a_{b}$
$\mathrm{C}_{\mathrm{f}}=(0,1,0)$
$a_{f}=0.4$
$c_{\text {red }}=0.4 * 0+(1-0.4) \star 0.9 * 1=0.6 * 0.9=0.54$
$c_{\text {green }}=0.4^{\star} 1+(1-0.4)^{\star} 0.9^{\star} 0=0.4$
$c_{\text {blue }}=0.4^{\star} 0+(1-0.4)^{\star} 0.9^{\star} 0=0$
$\left.a=0.4+(1-0.4)^{\star}(0.9)=0.4+0.6^{\star} 0.9\right)$
$c_{b}=(0.54,0.4,0)$
$a_{b}=0.94$

## Compositing Example II

$$
\begin{aligned}
& C_{f}=(0,1,1) \\
& a_{f}=0.4 \\
& \mathrm{Cf}_{\mathrm{f}}=(0,1,0) \\
& \mathrm{a}_{\mathrm{f}}=0.4 \\
& c_{\text {red }}=0.4^{\star} 0+(1-0.4)^{\star} 0.9^{\star} 1=0.6^{*} 0.9=0.54 \\
& c_{\text {green }}=0.4^{\star} 1+(1-0.4)^{*} 0.9^{\star} 0=0.4 \\
& c_{\text {blue }}=0.4 \star 0+(1-0.4)^{*} 0.9 * 0=0 \\
& \left.a=0.4+(1-0.4)^{\star}(0.9)=0.4+0.6^{*} 0.9\right) \\
& c_{b}=(0.54,0.4,0) \\
& a_{b}=0.94 \\
& C_{b}=(1,0,0) \quad c_{\text {red }}=0.4^{*} 0+(1-0.4)^{\star 0.94^{*} 0.54=0.6^{*} 0.94^{\star} .54=0.30} \\
& a_{b}=0.9 \\
& C_{\text {green }}=0.4^{\star 1}+(1-0.4)^{\star} 0.94^{\star} 0.4=0.6^{*} 0.94^{\star} .4=0.23 \\
& c_{\text {blue }}=0.4^{\star} 1+(1-0.4)^{\star} 0.94^{\star} 0=.4 \\
& \left.a=0.4+(1-0.4)^{\star}(0.94)=0.4+0.6^{*} 0.94\right)=.964 \\
& c=(0.3,0.23,0.4) \\
& a=0.964
\end{aligned}
$$

## Compositing Example II

$\mathrm{Cf}_{\mathrm{f}}=(0,1,1)$

$a_{f}=0.4$
$\cdots$

$$
\angle C_{f}=(0,1,0)
$$

## $c=a_{f}^{*} C_{f}+\left(1-a_{f}\right)^{*} a_{b}{ }^{*} c_{b}$ <br> $a=a_{f}+\left(1-a_{t}\right) * a_{b}$

$$
a_{f}=0.4
$$

$$
c_{\text {red }}=0.4^{*} 0+(1-0.4)^{\star} 0.9^{*} 1=0.6^{*} 0.9=0.54
$$

$$
c_{\text {green }}=0.4^{\star} 1+(1-0.4)^{\star} 0.9 \star 0=0.4
$$

$$
c_{\text {blue }}=0.4^{\star} 1+(1-0.4) \star 0.9 \star 0=0.4
$$

$$
\left.a=0.4+(1-0.4)^{\star}(0.9)=0.4+0.6^{\star 0} 0.9\right)
$$

$$
c_{b}=(0.54,0.4,0.4)
$$

$$
a_{b}=0.94
$$

## Compositing Example II

$$
\begin{aligned}
& \mathrm{Cf}_{\mathrm{f}}=(0,1,1) \\
& a_{f}=0.4 \\
& \begin{array}{l}
c=a_{r} *_{i}+\left(1-a_{t}\right) * a_{b} * c_{b} \\
a=a_{f}+\left(1-a_{f}\right) * a_{b}
\end{array} \\
& \angle C_{f}=(0,1,0) \\
& a_{f}=0.4 \\
& c_{\text {red }}=0.4 * 0+(1-0.4)^{\star} 0.9 * 1=0.6^{*} 0.9=0.54 \\
& c_{\text {green }}=0.4^{\star} 1+(1-0.4)^{\star} 0.9^{\star} 0=0.4 \\
& c_{\text {blue }}=0.4 * 1+(1-0.4) * 0.9 * 0=0.4 \\
& \left.a=0.4+(1-0.4)^{\star}(0.9)=0.4+0.6^{*} 0.9\right) \\
& c_{b}=(0.54,0.4,0.4) \\
& \mathrm{a}_{\mathrm{b}}=0.94 \\
& C_{b}=(1,0,0) \quad c_{\text {red }}=0.4^{\star} 0+(1-0.4)^{\star} 0.94^{\star} 0.54=0.6^{\star} 0.94^{\star} .54=0.30 \\
& a_{b}=0.9 \\
& c_{\text {green }}=0.4^{\star} 1+(1-0.4)^{\star} 0.94^{\star} 0.4=0.6^{\star} 0.94^{\star} .4=0.23 \\
& c_{\text {blue }}=0.4 \star 1+(1-0.4)^{\star} 0.94^{\star} 0.4=.23 \\
& \left.a=0.4+(1-0.4)^{\star}(0.94)=0.4+0.6^{\star} 0.94\right)=.964 \\
& c=(0.3,0.23,0.23) \\
& a=0.964
\end{aligned}
$$

## Compositing Orders

$$
\begin{aligned}
& c=a_{f}^{*} C_{f}+\left(1-a_{f}\right) * a_{b} * C_{b} \\
& a=a_{f}+\left(1-a_{f}\right) * a_{b}
\end{aligned}
$$

## Order Matters!

$$
\begin{array}{ll}
c=(0.3,0.23,0.4) & c=(0.3,0.23,0.23) \\
a=0.964 & a=0.964
\end{array}
$$

## The Emission-Absorption Model

How realistic is $\alpha$-compositing?
The emission-absorption model (Sabella 1988)


## The Emission-Absorption Model

 How realistic is $\alpha$-compositing?The emission-absorption model (Sabella 1988)


Initial intensity at $s_{0}$

$$
I(s)=I\left(s_{0}\right)
$$

Without absorption all the initial radiant energy would reach the point $s$.

## The Emission-Absorption Model

 How realistic is $\alpha$-compositing?The emission-absorption model (Sabella 1988)


Initial intensity at $s_{0}$

$$
I(s)=I\left(s_{0}\right) e^{-\tau\left(s, s_{0}\right)}
$$

## The Emission-Absorption Model

 How realistic is $\alpha$-compositing?The emission-absorption model (Sabella 1988)


Initial intensity at $s_{0}$

$$
I(s)=I\left(s_{0}\right) e^{-\tau\left(s, s_{0}\right)}
$$

## Optical depth $\tau$

Absorption $\kappa$

$$
\tau\left(s_{1}, s_{2}\right)=\int_{s_{1}}^{s_{2}} \kappa(s) d s
$$

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 How realistic is $\alpha$-compositing?The emission-absorption model (Sabella 1988)


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## Numerical Solution

We need to first estimate the optical depth by taking into account the absorption property of the material that the ray is traveling through.


$$
\text { Optical depth: } \tau(0, t)=\int_{0}^{t} \kappa(\hat{t}) d \hat{t}
$$

## Numerical Solution



Optical depth: $\tau(0, t)=\int_{0}^{t} \kappa(\hat{t}) d \hat{t}$
Approximate Integral by Riemann sum:

$$
\tau(0, t) \approx \sum_{i=0}^{\lfloor t / \Delta t\rfloor} \kappa(i \cdot \Delta t) \Delta t
$$

The area underneath the smooth curve $\boldsymbol{\kappa}(\boldsymbol{t})$ can be approximated as the sum of the areas of the individual rectangles.

## Numerical Solution



## Numerical Solution



Now we introduce opacity

$$
1-A_{i}=e^{-\kappa(i \cdot \Delta t) \Delta t}
$$

## Numerical Solution



## Numerical Solution

The area of each rectangle approximates


## Numerical Solution

$$
\begin{gathered}
e^{-\tilde{\tau}(0, t)}=\prod_{i=0}^{\lfloor t / \Delta t\rfloor}\left(1-A_{i}\right) \\
q(t) \approx C_{i}=c(i \cdot \Delta t) \Delta t \\
C_{f}^{b}=\sum_{i=f}^{b} \alpha_{i} C_{i} \prod_{j=f}^{i-1} T_{j} \quad \tilde{C}=\sum_{i=0}^{\lfloor T / \Delta t\rfloor} C_{i} \prod_{j=0}^{i-1}\left(1-A_{j}\right)
\end{gathered}
$$

can be computed recursively/iteratively!

## Numerical Solution



Note: we just changed the convention from $i=0$ is at the front of the volume (previous slides) to $i=0$ is at the back of the volume! can be computed recursively/iteratively:

$$
C_{i}^{\prime}=\left\{\begin{array}{l}
C_{i}+\left(1-A_{i}\right) C_{i-1}^{\prime} \\
C_{i}=A_{i} C_{\text {pure_color }}
\end{array}\right.
$$

## Numerical Solution


can be computed recursively/iteratively:


## Numerical Solution



Back-to-front
compositing

$$
C_{i}^{\prime}=C_{i}+\left(1-A_{i}\right) C_{i-1}^{\prime}
$$

Iterate from $i=0$ (back) to $i=m a x$ (front): $i$ increases
Front-to-back compositing

$$
\begin{aligned}
& C_{i}^{\prime}=C_{i+1}^{\prime}+\left(1-A_{i+1}^{\prime}\right) C_{i} \\
& A_{i}^{\prime}=A_{i+1}^{\prime}+\left(1-A_{i+1}^{\prime}\right) A_{i}
\end{aligned}
$$

Iterate from $i=m a x$ (front) to $i=0$ (back) : $i$ decreases

## Other Compositing - Average

Intensity



Depth

Synthetic Reprojection

