COS	SC 4330	SECOND MIDTERM	APRIL 2, 201
TI	his exam is closed boo l	k. You can have one page of notes. Please answe	er every part of every question.
	or each of the statement points), and <i>why</i> (3 p	nts below, indicate in one sentence whether thoints).	ne statement is true or false
(a)) Most servers use <i>t</i>	on-blocking receives.	
	FALSE, they use b	locking receives to avoid busy waits.	
(b)	Making all remote p	procedures <i>idempotent</i> greatly simplifies the task of	of the RPC server.
	TRUE, the client co	an resend any request for which it did not get o	a reply.
(c)) Peterson's algorithm	n for mutual exclusion does not work on <i>multico</i>	re architectures.
	FALSE, it only assu	umes that instructions cannot be executed out	of order.
(d)) A blocking send b	locks until the kernel accepts the message for	delivery.
	FALSE, it blocks u	ntil the receiver reads or retrive the message.	
(e)	A mutex semapho	ere can only have two correct values.	
	TRUE, these values	s are zero and one.	
(f)	Starvation is alwa	ys the result of a <i>deadlock</i> .	

2.	2. Answer in <i>one or two sentences</i> to the following questions: $(4 \times 5 \text{ points})$				
	(a)	What is the difference between a signal and a not if \mathbf{v}^{9}			

A monitor procedure P doing a notify() does not risk to lose control of the monitor as procedures waiting on its notify will have to wait until procedure P terminates before gaining control of the monitor.

(b)	What is the difference	between a	monitor	condition	and a	semaphore	?
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Monitor conditions have no value while semaphores do have one.			
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(c) What is the major disadvantage of the *at-most-once* semantics for remote procedure calls?

At-most-once semantics	does not pr	revent nor	detect part	rial executions o	f the remote	procedure.
	•		•			•

(d) What should a process do when it receives a *retransmission* of a message it has already received and acknowledged?

It should acknowledge that retransmission (in order to avoid additional retransmissions).

- **3.** Alice and Barbara have to go to New Orleans to present a paper at a computer conference. They decide to meet at Hobby airport before catching their flight. Their main problem is that they can only communicate through *blocking* send and receive primitives with *direct naming* such as:
 - bsend(Alice, buffer, nbytes)
 - breceive(Alice, buffer, &nbytes)

How will they be able to wait for each other using these two primitives? (2×5 points)

Alice will do:	Barbara will do:			
bsend(Barbara, buffer, nbytes)	breceive(Alice, buffer, &nbytes)			

4.	An interstate bus that can seat 44 passengers has a single door that lets passengers get in or out one by one at
	scheduled stops. Complete the two following methods to ensure that (a) the bus will never be overloaded and
	(b) passengers will not bump into each other when getting in or out the bus. (5×5 points)

```
Class bus {
    private int n_freeseats; // number of free seats
    private condition not_full;
    public void synchronized board bus() {
        if (n_freeseats == 0)
        no<u>t_full.wa</u>it;
        n_freeseats--;
    } // board_bus()
    public void synchronized leave_bus() {
        n_freeseats++;
        not_full.signal;
    } // leave bus()
    bus() {
        n freeseats = 44;
    } // constructor
  } // Class bus
```

5. What is wrong with the following solution to the mutual exclusion problem for *two processes*?

```
int lock[2]; // lock is the only global variable
lock[0] = lock[1] = 0; // 0 means FREE
enter_region(int pid) { // pid must be 0 or 1
     lock[pid] = 1; // 1 means BUSY
     while (lock[1-pid]);
} // enter_region
void leave_region(int pid){
     lock[pid] = 0;
} // leave_region
```

What happens? (5 points) The solution will cause a deadlock.

When does it happen? (10 points) When two processes try to enter the critical section in lockstep: each process will prevent the other from entering.