



# SOLUTIONS FOR THE SECOND 4330/6310 QUIZ

*Jehan-François Pâris*  
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# First Question

- Consider the following solution to the mutual exclusion problem and explain when it fails (5 points) and what happens then. (5 points)
- **shared int locked[2] = {0, 0}; // global variable**
- **void enter\_region(int pid) { // always 0 or 1  
    while (locked [1 - pid]); // busy wait  
    locked[pid] = 1; // reserve  
} // enter\_region**
- **void leave\_region(int pid) {  
    locked[pid] = 0;  
} // leave\_region**



# Answer

- When **two processes arrive in lockstep**  
then **both processes will enter the critical region.**



# Alternate first question

- Consider the following solution to the mutual exclusion problem and explain when it fails (5 points) and what happens then. **shared int locked[2] = {0, 0}; // global variable**
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} // enter\_region**
- **void leave\_region(int pid) {  
    locked[pid] = 0;  
} // leave\_region**



# Answer

- When **two processes arrive in lockstep**  
then **we have a deadlock.**



## Second question

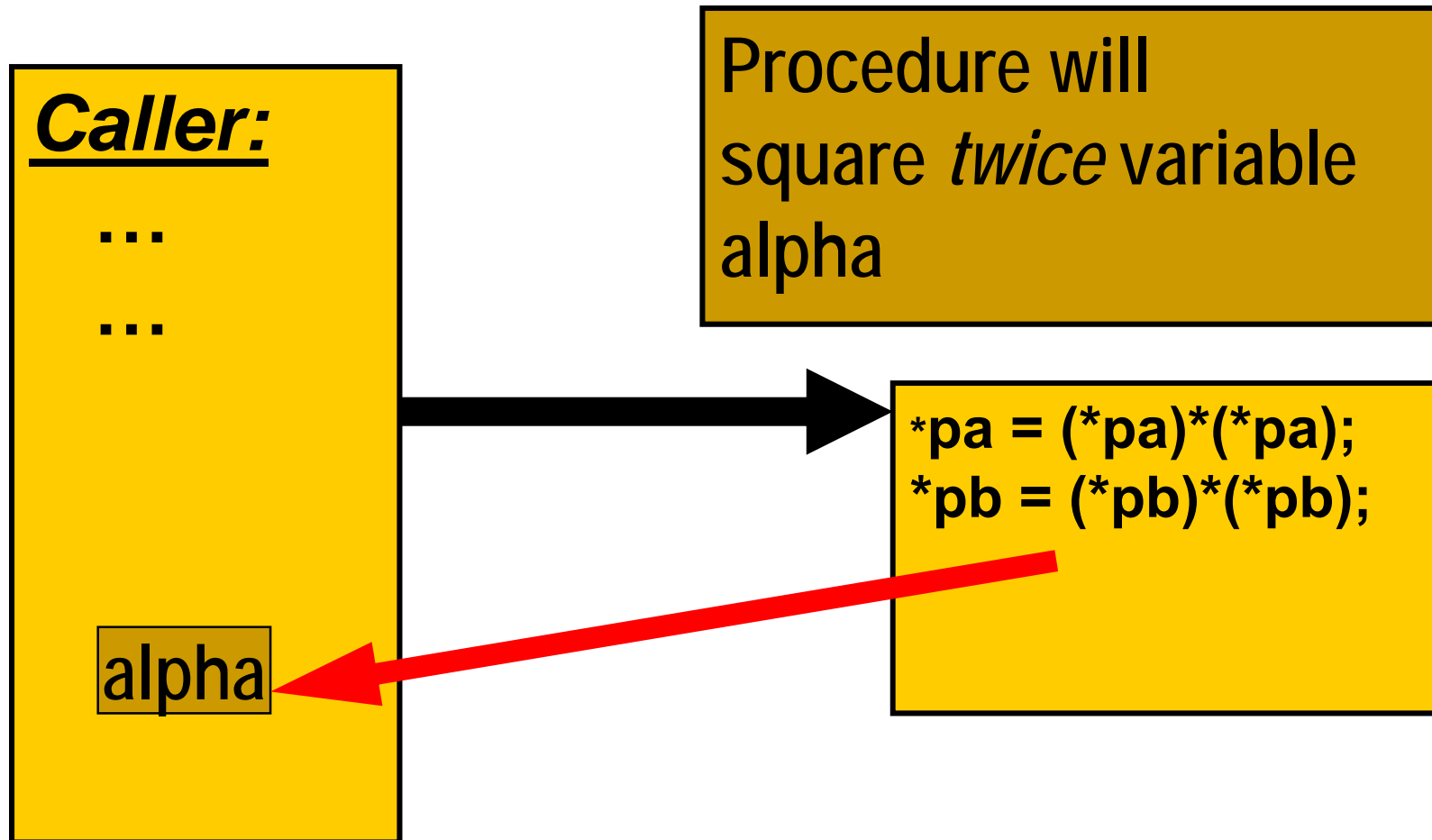
- Consider the function

- **void squarethem(int \*pa, int \*pb) {  
    \*pa = (\*pa)\*(\*pa);  
    \*pb = (\*pb)\*(\*pb);  
} // squarethem**

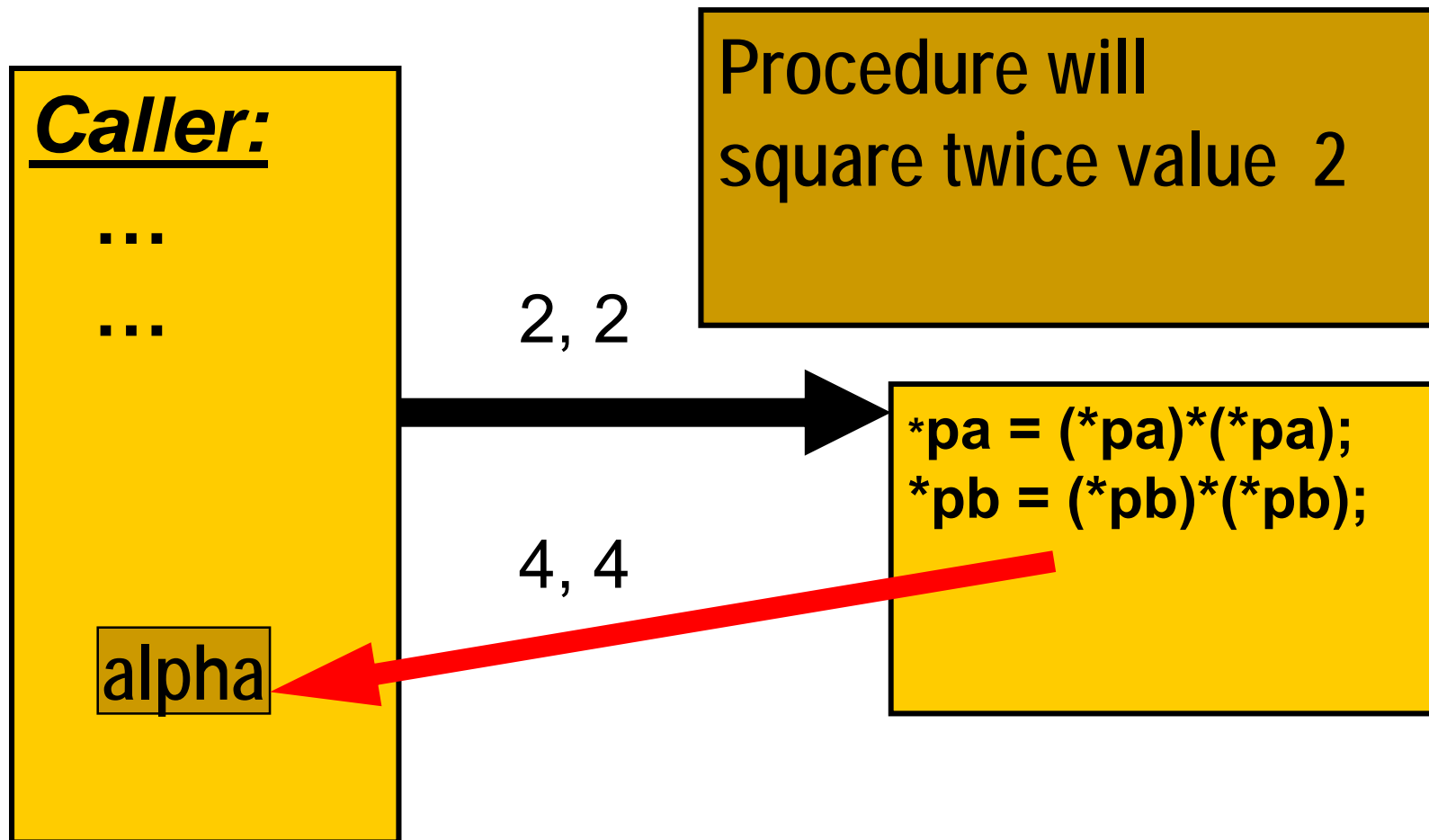
and assume the following calling sequence:

- **int alpha = 2;  
squarethem (&alpha, &alpha);**

# Passing by reference



# Passing by value and result







## Second question

- What will be the value of **alpha** *after the call* assuming that the call was:
  - A *conventional procedure call*?
    - $\text{alpha} = 2 \times 2 \times 4 = 16$
  - A *remote procedure call*?
    - $\text{alpha} = 2 \times 2 = 4$



# Alternate second question

- Assume now **alpha = 3**
- What will be the value of **alpha** *after the call* assuming that the call was:
  - *A conventional procedure call?*
    - **alpha =  $3 \times 3 \times 9 = 81$**
  - *A remote procedure call?*
    - **alpha =  $3 \times 3 = 9$**



# Third question

- Most scheduling policies decrease the priority of processes that have exhausted their slice of CPU time.
- Most programmers like to put all their signal operations at the end of their monitor procedures.
- Peterson's algorithm assumes the existence of shared variables.
- One cannot initialize binary semaphores.
- You cannot combine non-blocking sends and blocking receives.



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# Alternate third question

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# Alternate third question

- **FALSE:** Most scheduling policies increase the priority of processes that have exhausted their slice of CPU time.
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## Fourth question

- A cruising boat can carry up to 80 passengers. These passengers can embark or disembark through a narrow gangway that can accommodate one person at a time
- Complete the two following monitor procedures to ensure that neither the boat nor its gangway will ever be overloaded.
- **class Boat {  
    private int npassengers ;  
    private condition notfull;**



# Answer

- ```
public synchronized void embark(){  
    if (npassengers == 80)  
        notfull.wait;  
        npassengers++;  
    walk();  
} //embark
```
- ```
public synchronized void debark(){  
    walk();  
    npassengers--;  
    notfull.signal;  
} //debark
```





# Fifth question

- What are the sole correct values of X, Y and Z in the following System V.4 scheduler:

#ts_quantum	ts_tqexp	ts_slpret	ts_maxwait	ts_lwait	LVL
1000	X	1	50000	1	# 0
500	0	2	20000	2	# 1
200	1	3	10000	3	# 2
100	2	Y	10000	Z	# 3



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100	2	Y	10000	Z	# 3

- **X = 0**
- **Y = 3**
- **Z = 3**



# Alternate fifth question

- What are the sole correct values of X, Y and Z in the following System V.4 scheduler:

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500	0	2	20000	2	# 1
200	1	3	10000	3	# 2
100	2	4	10000	4	# 3
100	3	Y	10000	Z	# 4



# Alternate fifth question

- What are the sole correct values of X, Y and Z in the following System V.4 scheduler:

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500	0	2	20000	2	# 1
200	1	3	10000	3	# 2
100	2	4	10000	4	# 3
100	3	Y	10000	Z	# 4

- **X = 0**
- **Y = 4**
- **Z = 4**



## Sixth question

- What is the ***main disadvantage*** of the ***round-robin*** CPU scheduling policy?
  - **It causes too many context switches when the system is heavily loaded.**



## Sixth question

- Why does the ***web http protocol*** use streams instead of datagrams?
- **Because replies from an http server will not always fit in a single packet and we want these packets to arrive to the client in order without lost packets, damaged packets or duplicates.**



## Sixth question

- What is the ***main disadvantage*** of ***non preemptive*** CPU scheduling policies?
- They let CPU-bound processes monopolize the CPUs.



## Sixth question

- What is the main disadvantage of *spin locks*?
  - They waste CPU cycles while waiting for the lock (and generate context switches).





## Sixth question

- What is the difference between ***virtual circuits*** and ***streams***?
  - **Virtual circuits preserve message boundaries while streams do not.**



## Sixth question

- What is the difference between a ***blocking receive*** and a ***non-blocking receive***?
- A blocking receive waits until the process receives a message while a non-blocking receive does not.



## Sixth question

- What is the difference between a ***blocking send*** and a ***non-blocking send***?
- **A blocking send does not return until the message has been delivered to its recipient.**



## Sixth question

- How can you implement the ***at most once semantics*** in a remote procedure call package?
- **We should attach a sequence number to each message sent by a specific client and instruct the server to reject requests with duplicate sequence numbers.**